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Predicting TCP Throughput From Non-invasive Network Sampling

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Predicting TCP Throughput From Non-invasive Network Sampling

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Abstract— In this paper, we wish to derive analytic models that predict the performance of TCP flows between specified end-points using routinely observed network characteristics such as loss and delay. The ultimate goal of our approach is to convert network observables into representative user and application relevant performance metrics. The main contributions of this paper are in studying which network performance data sources are most reflective of session characteristics, and then in thoroughly investigating a new TCP model based on [1] that uses non-invasive network samples to predict the throughput of representative TCP flows between given end-points.

I. INTRODUCTION

As the Internet continues to evolve into the dominant commercial communications infrastructure, the need for service verification and quality monitoring is also increasing. This is reflected in the emergence of Service Level Agreements (SLAs) between providers and their (business) customers, which specify various levels of service guarantees that are to be met. Service guarantees are often specified using aggregate measures, e.g., a minimum bandwidth guarantee between sites, but the performance measures of real interest are usually the level of performance that individual users and applications experience. As TCP [2] traffic represents about 83% of the packets and 91% of the bytes on the Internet, monitoring TCP performance is a key step towards predicting, monitoring and analyzing network performance from an end-user perspective.

In this paper, we wish to derive analytic models that predict the performance of TCP flows between specified end-points using routinely observed network characteristics such as loss and delay. The ultimate goal of our approach is to convert network observables into representative user and application relevant performance metrics. In doing so, we seek to draw upon three different approaches to performance characterization – network sampling, application sampling and analytic modeling.

How does our approach relate to each of the above and to previous works on similar topics?

Service providers routinely sample performance and fault data in the network, and many of them advertise delay and loss information between city pairs as one form of feedback to customers. For scalability reasons, carriers use non-invasive sources; for example, loss and throughput data available from router SNMP MIBs, or delay estimates obtained from probes exchanged between routers; rather than invasive information obtained from stateful inspection of individual flows. In order for this data to be meaningful to individual users, it must be transformed into user/application specific metrics. Undertaking this transformation in the context of TCP is the focus of this paper.

An alternative approach to user relevant monitoring is through application sampling. Several vendors offer SLA assurance software for periodically initiating and measuring web transfers, file transfer, email and other services between predefined end-points. While quite simple to implement and use, application sampling suffers from a number of limitations. Such sampling cannot distinguish between different factors that contribute to application performance. For instance, sampling web download performance composites DNS lookup times, web server latencies, as well as congestion in different network segments. If the hosting provider is different from the network provider, it is difficult to decide which of them is responsible for poor performance. The lack of an underlying model and inability to decompose result in unnecessary over-sampling. For instance, web page download times cannot be re-used to predict FTP performance; nor can information be shared between web downloads passing through the same bottleneck. Rather than treat the network as a “black box”, our approach allows information sharing between carrier and customer, with scalability and infrastructure savings as primary advantages.

Of particular relevance to this paper is the extensive literature on analytic modeling of TCP behavior targeting different environments [3], [4], [5], [1], [6], [7], [8], [9], [10]. A direct approach to our goal would be to use network data to estimate model parameters. In doing so, we need to consider two related issues. How should the network be sampled? By polling the MIBs in the routers or by probing the network with end-to-end pings, for instance? The second issue is that of transforming the raw samples into input parameters of the chosen model. We ruled out several analytic models because of the infeasibility of estimating their input parameters. For instance, some models use parameters such as “loss events” (the event of a TCP flow reducing its congestion window) that cannot be estimated from non-invasive network observables; some others depending on loss correlations between successive packets of a TCP session can work only with a mechanism that inspects packets on a per-session granularity; yet others are tailored to restricted environments. Given such constraints, we tried in-

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1See http://www.caida.org/outreach/papers/ for recent data.
stead to pick an analytically sound and well-tested model, and see how far we could go in retro-fitting network observables to model inputs. The model proposed in [1] (henceforth called the Amherst Model), turned out to be a good starting point for our investigations. While the straightforward approach of directly estimating Amherst Model parameters from network samples produced inaccurate results (see Section III), we were able to produce a more reliable variant based directly on network observables.

A. Contributions

The motivation for this paper is the need for user relevant performance metrics based on observable network data. Our work is a modest but necessary step towards this ambitious goal – we investigate the selection and transformation of network data into metrics based on the predicted throughput of long-lived TCP flows.

The main contributions of this paper are two-fold. First we investigate how to sample the network to obtain reliable and accurate estimates of important network characteristics like Round-trip time (RTT) and loss rates. In this respect, it is important to understand how and when network observables are good estimators of TCP session observables. The importance of this contribution is evident as even the most accurate TCP model will be rendered ineffective if the required input parameter values cannot be determined accurately. The second contribution is the development of a model capable of predicting steady state TCP throughput reasonably accurately, using only the input parameters that can be easily obtained in a non-invasive fashion. As mentioned earlier, the new model builds on the Amherst model of [1], but includes a number of non-trivial enhancements that improved overall model accuracy. The model was evaluated for a wide range of configurations using both testbed experiments and simulations and found to predict steady state TCP throughput reasonably well, at least in scenarios where the network monitoring information available to the model was itself reasonably accurate.

The rest of this paper is structured as follows. Section II discusses the feasibility and limitations of sampling network information. It reviews the various non-invasive methods we rely on, as well as their ability to estimate network properties accurately in variety of settings. Section III first examines the feasibility of transforming network observables into parameter estimates in the Amherst model. The resulting inaccuracies in TCP throughput prediction lead us to develop a new model better suited to the use of network information acquired in a non invasive manner. The performance of the new model is investigated for a wide range of network conditions and loss rates in Section IV, while Section V summarizes the findings of the paper.

II. Non-invasive Estimation of Network Properties

The information needed to predict the throughput of TCP flows consists of session level information such as packet size, retransmission timer granularity, maximum congestion window size, use of delayed acks, etc., and of network level information such as sequence of successive round trip times and or losses. We are interested in the latter category, as session level information can be regarded as chosen a priori while defining representative flows. Further, analytic models of TCP performance use some simplified characteristic of the delay and loss sequences as predictors, rather than the sequences themselves. In this section, we examine loss and delay characteristics that can be derived from non-invasive network sampling, with a view to selecting and developing models that use them.

A. Network based parameters: What loss characteristics to estimate?

In predicting TCP throughput, there are a number of “plausible” loss models one can envision. The simplest one assumes random losses, i.e., packet losses are modeled as a sequence of independent Bernoulli trials with parameter equal to the loss rate. Such a parameter is easily estimated from the ratio of the numbers of lost and transmitted packets. More sophisticated models assume that losses are correlated in nature. Generally, these models assume that losses occur with probability p as long as the system is not “congested”, and that they occur with probability p′ ≥ p after the “first” loss, which is used to identify the start of a congestion period. These models require the estimation of two parameters, p and p′, as well as the determination of the duration of a congestion period once it has started. Neither of these tasks is straightforward, especially if they are to be performed using non-invasive procedures. Hence in this paper, we have presented only the random loss model. The results indicate that the model provides fairly accurate estimates of long term TCP throughput for a wide range of network conditions and loss rates.

B. Techniques for Non-invasive Estimation: Polling and Prob- ing

This section focuses on non-invasive estimation procedures and their use in estimating parameters of interest in the context of TCP throughput prediction. This means that rather than examining tcpdump traces or performing flow level monitoring to estimate loss probabilities, we would like to rely instead on information that is routinely gathered using basic network probing and polling mechanisms. The characteristics as well as the pros and cons of these two mechanisms are reviewed next.

Probing: Probes can easily be implemented using existing mechanisms such as ping packets sent from ingress towards egress routers. The ratio of probe packets lost and sent gives an estimate of loss rate while each reply to the ping probe provides a sample for the RTT. RTT samples obtained by ping probes can be used to maintain smoothed RTT (srtt) and smoothed mean deviation in RTT (rttvar) values [11], [12]. These values along with that of clock granularity (G) can be used to estimate 'first' retransmission timeout value (T0) using the well-known formula [11], [13]:

$$T0 = srtt + max(G, 4 \times rttvar)$$

(1)

If the retransmission timeout value comes out to be less than 1 second, it is rounded up to 1 second [11]. Hence, it is not crucial to have a very good estimate for rttvar unless it will make significant difference to T0 values.
The main advantage of probing methods is that they sample a complete network segment. As a result, they can provide direct estimates of end-to-end loss probabilities and round-trip times. However, our experiments suggested that while probing methods provide a good estimate of RTT (and timeout durations), the performance is not quite satisfactory for estimating loss rates as observed by the TCP flows [14]. (1) Probe packets do not sample network queues in the same fashion as TCP flows. We tried to rectify this problem by emulating the bursty or 'ack paced' nature of TCP flows in our probing applications. Specifically, we experimented with a back-to-back and an ack-paced probing algorithm. Back-to-back probing involves sending all the packets in a single round of probing back to back while in ack-paced probing the timing between probe replies determines the timing between probe packets in next round of probing. However, these specialized probing applications resulted in only a marginal improvement in the loss rate estimates. (2) Probe loss estimates are significantly affected by the number of packets in a round of probing, the inter-probe delay, the frequency of probing rounds and the packet size used in probes. (3) Loss estimates obtained from probes converge slowly. (4) Probe packets do not always follow the same path or get the same treatment as the data packets.

In figure 1, we show sample simulation results regarding the performance of the probing techniques in estimating loss rates for a set of TCP flows passing through two congested routers with RED [15] buffers. In these simulations, the probing application sent 4 probes (of same size as the packets of TCP flows) in each round of probing and was frequent enough to consume 0.5% of the bottleneck link bandwidth. Other simulation details can be seen later in the paper in section IV-B. It can be observed that ack-paced probing provides much better estimates than back-to-back probing but still the performance is far from satisfactory. The figure also shows that the loss rate estimates obtained from SNMP MIBs are quite good. These and other similar results led us to conclude that it is not easy to obtain accurate estimates of network loss rates as observed by TCP flows using probing methods. As we discuss next, a much better job can be done by polling SNMP MIBs on the routers.

Polling: This refers to the periodic querying of the SNMP MIBs maintained in the routers to retrieve performance data. For example, the Interfaces table of SNMP MIB-II [16] can provide information regarding the number of transmitted and lost packets and the length of the output packet queue. The number of transmitted and lost packets can be used to obtain loss rate at the router while the length of the output packet queue can provide an estimate for the queueing delays which can be combined with propagation delays to obtain an estimate for the round trip time. One advantage of router MIBs is that they automatically aggregate statistics over time and do not require the transmission of numerous (probe) packets into the network. The overhead of MIB polling is primarily dictated by the frequency at which the polling occurs, and there is a trade-off between the associated message and processing overhead, and the accuracy with which changes in network parameters are being tracked. The MIB statistics are typically maintained at the interface level, so that the performance measures they track are for the aggregate traffic crossing that interface, and as with probes, those can differ from what individual TCP flows experience. In this respect, we found that the buffer management policy used at the interfaces can have a significant effect. For RED [15] buffers, the random nature of packet drop tends to minimize the difference between aggregate and individual loss rates. However, for drop tail buffers the differences can be significant especially for the small default buffer sizes. In figure 2, we present the loss rates experienced by TCP flows with different RTTs and the MIB loss rate for RED and droptail buffers in our testbed experiments. Clearly, with default sized droptail buffers, the MIB loss rate is not a good estimate for the loss rates suffered by TCP flows. Our simulation results indicate that our droptail the situation does not improve even with increased buffer sizes [14]. However, for RED buffers, the MIB loss rate can serve as a good estimate for TCP flow loss rates with accuracy improving as the buffer size increases. The improvement in estimate accuracy with increased buffer size can be explained as a result of increased randomness in packet drop.

Since SNMP MIBs provide information specific to a single router (interface), generating end-to-end statistics requires combining MIB information from all bottleneck routers on the path of a flow. Generally a TCP flow’s path on the Internet is characterized by just one or two bottlenecks (on access links to high capacity backbone). Hence the problem of obtaining end-to-end loss rate is not that severe. Further, in general, the two bottleneck links on the path of a flow will be quite far away from each other and the traffic causing congestion in these links will be quite unrelated. Thus, it may be assumed that the losses at different bottleneck routers on the path of a flow are independent in nature and can be accordingly combined to obtain end-to-end loss rates. Figure 1 shows sample simulation results in this regard. It can be seen that 'independent loss' assumption provides quite satisfactory estimates of actual end-to-end loss rates.

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2Testbed details are provided in section IV-A.
III. TCP THROUGHPUT PREDICTION MODELS BASED ON NON-INVASIVELY OBTAINED PARAMETERS

In this section, we first briefly review why it is difficult to apply popular Amherst model to the setting where network parameters are assumed to be obtained using only non-invasive procedures. This is then followed by the development of several modifications and enhancements to the model, which allow for reasonably accurate predictions of TCP throughput based only on information obtained through non-invasive procedures.

A. Motivation for Developing New Models

We assume that the reader is familiar with the Amherst Model [1]. The model predicts the throughput of a TCP flow based on an expression that involves several parameters, including average RTT, first time-out duration \( T_0 \), and more important for our purpose, the probability \( p \) of “first” packet loss in an epoch. Correctly estimating this parameter is, therefore, key to an accurate throughput prediction. In [1], this estimation was carried out based on the number of “loss events” (triples duplicate acks and time-outs) observed for the flow itself. The identification of loss events requires invasive flow level awareness. Nevertheless, our first attempt was to determine if it was possible to obtain a reasonable estimate for the first packet loss used by the Amherst model, by using only non-invasive procedures such as the ones described in Section II.

The approach we took was to develop a procedure for computing the first packet loss \( p \) needed by the Amherst model, from the measured overall loss rate \( L \) obtained using non-invasive procedures (Appendix A). Performing such a mapping required relating the observed number of losses to the number of lost packets (after the first loss) given by the loss model used in the Amherst model. Unfortunately, because the Amherst model assumes that, subsequent to the first packet loss, all the remaining packets in the window are also lost, the resulting inversion of the observed loss rate \( L \) into a first packet loss probability \( p \), is highly inaccurate. As a result and as shown in Figure 3, the resulting throughput estimates are also inaccurate. Note that this assumption regarding packet losses is of very limited consequence in the environment assumed by the Amherst model, i.e., when an accurate estimate is readily available for the first packet loss probability \( p \). This is, however, not true when we need to derive an estimate for \( p \) based on the overall observed loss probability. In such a setting, the loss model used for relating these two quantities is of significant importance.

Our next step was, therefore, to determine how to modify the Amherst model, in order to use different loss models, i.e., models that rely on parameters that can be estimated using non-invasive procedures, such as the random loss model introduced in Section II.

In the random loss model, packets are lost randomly with a loss probability \( p \). For such a loss model, the probability \( P(i, W) \) that after the first packet loss in an epoch, a total of \( i \) packets, including the first loss, are lost in the following window of size \( W \) is given by:

\[ P(i, W) = \binom{W}{i} (1-p)^{W-i} p^i \]

where \( \binom{W}{i} \) is the binomial coefficient.

3. An epoch corresponds to a period of time during which the TCP flow is in congestion avoidance mode and regularly increasing its window.

4. As illustrated in [1], the Amherst model gives reasonably accurate TCP throughput estimates.
TCP. However, in TCP Reno implementations, which still comprise about 60% of currently deployed implementations [18], the congestion window can be reduced by more than a half depending on the number of losses. This is significant, as it can be shown that for the same total number of packets transmitted in an epoch, the duration of the epoch, i.e., the number of rounds, is larger when the initial window size is smaller. The implication of this result is that always starting with the largest possible initial window size, as is done in the Amherst Model, can translate in over-estimates of the actual throughput, because it under-estimates the amount of time needed to transmit a given number of packets. Hence, it is desirable to develop a model that relates the initial window size to the final window size in the previous epoch and to the number of losses that ended the epoch.

For that purpose, we assume, as in the Amherst Model, that the steady state of a flow can be characterized by a sequence of similar epochs, with each epoch starting with a window of size $W_i$ and ending with a window of size $W_f$. Let $Q(m, W_f)$ be the probability that $W_i$ equals $\frac{W_f}{m}$. We assume that $W_i$ never goes below $\frac{W_f}{8}$. After an analysis similar to the one performed for retransmission timeout probability (details in [14]), we can obtain the following expressions for $Q(m, W_f), m = 1, 2, 3$:

$$Q(1, W_f) = \begin{cases} 1 & \text{if } W_f < 4 \\ P(1, W_f) & \text{otherwise} \end{cases}$$

$$Q(2, W_f) = \begin{cases} 1 - Q(1, W_f) & \text{if } W_f < 10 \\ P(2, W_f) & \text{otherwise} \end{cases}$$

$$Q(3, W_f) = 1 - Q(1, W_f) - Q(2, W_f)$$

where as before, $P(n, W_f)$ is the probability of losing $n$ packets out of a window of $W_f$ packets starting with the first lost packet. Thus, the initial window size $W_i$, instead of always being set to $\frac{W_f}{2}$, is given by:

$$W_i = \sum_{n=1}^{3} Q(n, W_f) \frac{W_f}{2^n}$$

In the next section, we bring together the two modifications we have just outlined and the random loss model discussed earlier, to generate a new TCP throughput prediction model. As stated before, our goal is to develop a modified model that can operate on the basis of global network performance parameters that can be estimated using non-invasive procedures.

B. A Modified Model for Bulk TCP Throughput Prediction

In this section, we present a ‘cyclical’ model for bulk transfer TCP throughput prediction. By ‘cyclical’ we mean that the steady state of a Reno TCP flow can be characterized as a sequence of epochs during which the flow increases its congestion window linearly from an initial value $W_i$ to a final value $W_f$ with a slope of 1 packet per $b$ rounds. Here a round corresponds to the time during which the TCP flow sends a congestion window worth of packets and $b$ is the number of packets received before a TCP destination sends an ack back to the source. As in the Amherst Model, we assume that the duration of a round is independent of the congestion window size, and that an epoch consists of a congestion avoidance phase possibly followed by
a timeout phase. For simplicity, we ignored packets sent during the slow start and fast retransmit phases, although the latter were taken into consideration when computing time-out probabilities [14].

The number of packets sent in the congestion avoidance phase of an epoch is determined by the packet loss probability \( p \). Starting from the beginning of an epoch, let the \( o \)th packet be the first one to be lost. The returning acks of the preceding successfully transmitted packets in the window will allow the TCP flow to send \( W_f - 1 \) more packets before the packet loss is detected. Thus, the total number of packets sent in the congestion avoidance phase of the epoch is given by \( Y = \alpha + W_f - 1 \).

Now, the probability that \( \alpha = k \) is equal to the probability that \( k - 1 \) packets were successfully transmitted before a loss occurs, which for the random loss model we consider is given by

\[
P[\alpha = k] = (1 - p)^{k-1} p, \quad k = 1, 2, \ldots
\]  

Thus, the expected value of \( \alpha \) is

\[
E[\alpha] = \sum_{k=1}^{\infty} (1 - p)^{k-1} pk = \frac{1}{p}
\]  

As a result, the expected number of packets sent in the congestion avoidance phase of an epoch is:

\[
E[Y] = \frac{1 - p}{p} + W_f
\]

The number of packets sent in the congestion avoidance phase of an epoch can also be written in terms of \( W_i \) and \( W_f \). After the first lost packet, the TCP flow sends \( W_f - 1 \) more packets before the packet loss is detected. Some of these packets are sent in the same round as the first lost packet, and the remaining \( \beta \) packets constitute what we term another short round. Therefore the total number of packets sent in the congestion avoidance phase of an epoch can also be written as:

\[
Y = \frac{b}{2}(W_f + W_i)(W_f - W_i + 1) + \beta
\]

The expected value of \( \beta \) can be derived as follows. If \( \beta \) packets are sent in the last short round, the position of the first lost packet in the penultimate round was \( \beta + 1 \). The probability that the first packet is lost at position \( \beta + 1 \) given that at least one packet was lost in the window of size \( W_f \) is equal to

\[
\frac{p(1-p)^\beta}{1-(1-p)^W_f}.
\]  

Therefore, the expected value of \( \beta \) is given by:

\[
E[\beta] = \sum_{i=0}^{W_f-1} \frac{(1-p)^i}{1-(1-p)^W_f} = \frac{1 + (W_f - 1)(1 - p)^W_f}{1 - (1 - p)^W_f}
\]  

Thus, the expected number of packets sent in the congestion avoidance phase of an epoch can be expressed as:

\[
E[Y] = \frac{b}{2}(W_f + W_i)(W_f - W_i + 1) + \frac{1 + (W_f - 1)(1 - p)^W_f}{1 - (1 - p)^W_f}
\]  

Equations (10) and (13) provide two different ways for expressing the total number of packets sent in the congestion avoidance phase of an epoch. By equating these two expressions and simplifying we get:

\[
W_f = \frac{b}{2} (W_f + W_i)(W_f - W_i + 1)(1 - (1 - p)^W_f)
\]  

Equation (14) together with equation (7) can be used to eliminate the unknown \( W_i \) and express \( W_f \) as a function of \( p \). It can be shown that under the random loss model, for a given \( p \), the resulting equation admits a unique solution for \( W_f \) [14]. Once \( W_f \) is known, \( W_i \) can be computed from equation (7), and the expected number of packets \( E[Y] \) sent during the congestion avoidance phase can, therefore, be computed from equation (13). It now remains to compute the duration of an epoch in order to be able to predict the throughput of a TCP flow.

An epoch consists of a congestion phase possibly followed by a retransmission time-out phase. Let \( X(W_i, W_f) = b(W_f - W_i + 1) \) be the number of rounds during which the congestion window increases from its initial value \( W_i \) to its final value \( W_f \) with a slope of 1 packet per \( b \) rounds. Thus, after including the final short round, the duration of the congestion avoidance phase of an epoch is given by \( (X(W_i, W_f) + 1)RTT \) where \( RTT \) is the average duration of a round.

From equation (3), we know how to compute \( P_{TO}(W_f) \), the probability that a congestion avoidance phase is followed by a retransmission timeout phase when the final congestion window is \( W_f \). It, therefore, only remains to compute the number of packets that may be transmitted during this phase, as well as its duration. Using the same approach as suggested in [1], these quantities can be determined to be given by:

\[
E[R] = \sum_{k=1}^{\infty} kP[R = k] = \frac{1}{1 - p}
\]

\[
E[Z_{TO}] = T_0 \left( 1 + p + 2p^2 + 4p^3 + 8p^4 + 16p^5 + 32p^6 \right) \frac{1}{1 - p}
\]

where \( E[R] \) is the expected number of packets sent in the timeout phase and \( E[Z_{TO}] \) is the expected duration of the timeout phase. Also \( P[R = k] \) is the probability that \( k \) packets are sent in the timeout phase and is given by \( p^{k-1}(1 - p) \). \( T_0 \) is the average duration of the "first" timeout period.

Based on the above equations, we are now in a position to compute the steady state throughput of a TCP flow (in packets per second):

\[
B(p) = \frac{E[Y] + P_{TO}(W_f)E[R]}{X(W_i, W_f) + 1)RTT + P_{TO}(W_f)E[Z_{TO}]}
\]

In case \( W_f \) turns out to be more than \( W_{max} \), the maximum permissible congestion window size, the formula above changes to:

\[
B(p) = \frac{E[Y] + P_{TO}(W_{max})E[R]}{RTT(U + V + 1) + P_{TO}(W_{max})E[Z_{TO}]}
\]

where \( U \) and \( V \) are expected number of rounds during which the congestion window increases from its initial value to \( W_{max} \) and then remains constant until the round where packet loss occurs. The derivation is simple and details can be seen in [14].

The expressions for \( U \) and \( V \) can be obtained to be:

\[
U = \frac{3}{2} \sum_{m=1}^{W_{max}} \min(Q(m, W_{max}), \frac{W_{max}}{m}) - \frac{W_{max}}{2m^2}
\]
Before concluding the section, we reiterate the differences between the Amherst Model and the throughput prediction model derived above:

1) The required input loss rate for the new model is simply the average loss rate effective during the lifetime of the TCP Reno flow.

2) The new model calculates the retransmission timeout probability and initial congestion window size in an epoch based on the final window size in the previous epoch and the number of losses that ended the epoch.

Now that we have completed the derivation of a TCP throughput prediction model that relies on network parameters derived using non-invasive estimation procedures, it remains to evaluate the accuracy achieved by this new model.

IV. PERFORMANCE EVALUATION

The throughput prediction model described in the previous section was evaluated thoroughly for a wide range of scenarios using both testbed experiments and NS2 [19] simulations. Testbed experiments allowed us make a good assessment of the non-invasive estimation methods and the performance of our throughput prediction model for the scenario where there is a single congested link in the path of TCP flows. We used NS2 simulations to perform the same assessment for the scenario with two congested links in the path. In the following we describe the testbed and simulation setups and then present the key performance results. A comprehensive presentation of the simulation and testbed results can be found in [14].

A. Testbed Experiments

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BEFORE CONCLUDING THE SECTION, WE REITERATE THE DIFFERENCES BETWEEN THE AMHERST MODEL AND THE THROUGHPUT PREDICTION MODEL DERIVED ABOVE:

1) THE REQUIRED INPUT LOSS RATE FOR THE NEW MODEL IS SIMPLY THE AVERAGE LOSS RATE EFFECTIVE DURING THE LIFETIME OF THE TCP RENO FLOW.

2) THE NEW MODEL CALCULATES THE RETRANSMISSION TIMEOUT PROBABILITY AND INITIAL CONGESTION WINDOW SIZE IN AN EPOCH BASED ON THE FINAL WINDOW SIZE IN THE PREVIOUS EPOCH AND THE NUMBER OF LOSSES THAT ENDED THE EPOCH.

NOW THAT WE HAVE COMPLETED THE DERIVATION OF A TCP

THROUGHPUT PREDICTION MODEL THAT RELIES ON NETWORK PARAMETERS DERIVED USING NON-INFRINGEMENT ESTIMATION PROCEDURES, IT REMAINS TO EVALUATE THE ACCURACY ACHIEVED BY THIS NEW MODEL.

IV. PERFORMANCE EVALUATION

THE THROUGHPUT PREDICTION MODEL DESCRIBED IN THE PREVIOUS SECTION WAS EVALUATED THOROUGHLY FOR A WIDE RANGE OF SCENARIOS USING BOTH TESTBED EXPERIMENTS AND NS2 [19] SIMULATIONS. TESTBED EXPERIMENTS ALLOWED US MAKE A GOOD ASSESSMENT OF THE NON-INFRINGEMENT ESTIMATION METHODS AND THE PERFORMANCE OF OUR THROUGHPUT PREDICTION MODEL FOR THE SCENARIO WHERE THERE IS A SINGLE CONGESTED LINK IN THE PATH OF TCP FLOWS. We used NS2 simulations to perform the same assessment for the scenario with two congested links in the path. In the following we describe the testbed and simulation setups and then present the key performance results. A comprehensive presentation of the simulation and testbed results can be found in [14].

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TABLE II

<table>
<thead>
<tr>
<th>Simulation ID</th>
<th>Bottleneck Bandwidth</th>
<th>RoundTrip Propagation Delay</th>
<th>Buffer Size</th>
<th>Congestion Router</th>
</tr>
</thead>
<tbody>
<tr>
<td>T1</td>
<td>50/250ms,100/200ms</td>
<td>50,100,200 packets</td>
<td>30-100 bytes</td>
<td>Buffer at No. 50, 100, 200 packets</td>
</tr>
<tr>
<td>T2</td>
<td>50/250ms,100/200ms</td>
<td>50,100,200 packets</td>
<td>30-100 bytes</td>
<td>Buffer at No. 50, 100, 200 packets</td>
</tr>
</tbody>
</table>

TABLE III

<table>
<thead>
<tr>
<th>Common Simulation Parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCP Flavors</td>
</tr>
<tr>
<td>Max CWND, Recv Window</td>
</tr>
<tr>
<td>Deflated Ack</td>
</tr>
<tr>
<td>Time Simulation</td>
</tr>
<tr>
<td>Simulation time</td>
</tr>
<tr>
<td>Packet Loss</td>
</tr>
<tr>
<td>Bottleneck Bandwidth</td>
</tr>
<tr>
<td>Round Trip Propagation Delay</td>
</tr>
<tr>
<td>Buffer Size at Congested Router</td>
</tr>
<tr>
<td>Access Link Bandwidth</td>
</tr>
</tbody>
</table>

B. Simulation Configuration and Parameters

Figure 5 shows the two congested routers simulation configuration used to evaluate the performance of estimation mechanisms and the throughput prediction model. The common simulation parameters are listed in Table III. In the simulations, a set S-D of 24 Reno TCP flows each with same RTT (R1) crossed the two congested router links, link1 and link2. Both link1 and link2 were congested as a result of traffic generated by flow sets S1-D1 and S2-D2, respectively. Each one of these sets consists of 24 Reno TCP flows with same RTTs (R2). All simulations were run for a period of 256 seconds which was sufficient to allow all flows to achieve their steady state behavior. Further, to avoid synchronization among flows, the flows were started at random times within the first second of simulation run. The simulation results shown in the paper correspond to S-D flows.

C. Results

In order to facilitate the presentation of results for the different possible variations of parameters, testbed experiments and simulations were numbered according to their combination of parameters (Tables I and II). Based on this numbering, the parameters for a particular experiment/simulation can be ascertained from its ID. E.g. the simulation ID 30 in Table II refers to the simulation with bottleneck bandwidth T3, two RTT (R1/R2) values of 100/2000ms and buffer size of 200 packets.

The key performance evaluation results are presented in figures 6 and 7. These figures show the average throughput achieved by TCP flows with same RTT and the predictions made by our throughput prediction model using actual loss rates and those obtained from SNMP MIBs. The results shown here correspond to RED simulations and testbed experiments. The loss rate range covered in these experiments can be seen in figures 1 and 2. Our throughput prediction model performed equally well for droptail experiments when actual loss rates were used as input [14]. However, since loss rate estimates obtained from SNMP MIBs were not good in droptail experiments, the performance of the throughput prediction model also suffered in consequence. The results clearly indicate that the new model works pretty well over a large range of loss rates and network conditions when reasonably accurate estimates for the loss rates are available. Note that the loss rate estimates obtained from SNMP MIBs in RED experiments result in quite accurate TCP throughput prediction. Further, the independent losses assumption used to combine loss rates at individual bottlenecks into end-to-end loss rate seems to give satisfactory performance.

V. Conclusion and Future Work

This paper has been concerned with developing and evaluating models for predicting the steady state of representative TCP flows between fixed end-points, based on non-invasively obtained network data. The motivation for this work is to enable the transformation of data readily available to service providers into user and application specific metrics. As existing TCP models do not readily fit the task at hand, we chose the popular Amherst model as a starting point and developed a modified cyclical model to suit our purposes. We also investigated the appropriateness and limitations of polling and probing as techniques for generating suitable inputs for our model.

Our model has been validated using simulations and as well as testbed experiments under a variety of scenarios. However, there are several limitations of this work, some of which can be remedied with further research.

1) Our work focuses on long-lived TCP Reno flows. Metrics based on short-lived flows, as well as other TCP flavors need to be investigated [9].

2) Our work assumes that one can determine the congestion points affecting flows between two end-user sites. This assumption is valid when network access points are the principal bottlenecks. However, more sophisticated techniques for determining congestion points need to be coupled with our techniques, in order to select network samples relevant to a user.

3) The biggest task for the future is to undertake an assessment of the relevance of simple metrics (DNS lookup times, TCP throughput predictions) or their combinations to application performance (Web downloads, FTP transfer times).

REFERENCES

Fig. 6. Throughput Prediction with Actual Loss Rates.

Fig. 7. Throughput Prediction with MIB Loss Rates.
The expected number of packets lost, \( N \), in an epoch in the Amherst model is the sum of expected number of packets lost in the congestion avoidance phase plus those lost in the timeout phase. An expression for \( N \) can be obtained that involves \( p \) and uses the Amherst model assumption that after the first loss the remaining packets in the round are also lost. This gives:

\[
N = \sum_{n=1}^{W} \left( W - n + 1 + p \sum_{i=0}^{n-1} (1 - p)^{i} - 1 \right) \frac{(1 - p)^{n-1} - 1}{1 - (1 - p)^{W}} + \hat{Q}(W) \left( \frac{1}{1 - p} - 1 \right)
\]

As a result, the measured overall loss rate \( L \) and the first packet loss probability \( p \) used in Amherst model are related through the following expression \( L = \frac{N}{E[V]} \). It can be shown that the rhs is a monotonically increasing function of \( p \). Hence the value of \( p \) can be numerically computed for any given \( L \).