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Processing XML Streams with Deterministic Automata and Stream Indexes

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Processing XML Streams with Deterministic Automata and Stream Indexes

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May 11, 2004

Abstract

We consider the problem of evaluating a large number of XPath expressions on a stream of XML packets. We contribute two novel techniques. The first is to use a single Deterministic Finite Automaton (DFA). The contribution here is to show that the DFA can be used effectively for this problem: in our experiments we achieve a constant throughput, independently of the number of XPath expressions. The major issue is the size of the DFA, which, in theory, can be exponential in the number of XPath expressions. We provide a series of theoretical results and experimental evaluations that show that the lazy DFA has a small number of states, for all practical purposes. These results are of general interest in XPath processing, beyond stream processing. The second technique is the Streaming Index (SIX), which consists of adding a small amount of binary data to each XML packet that allows the query processor to achieve significant speedups. As an application of these techniques we describe the XML Toolkit (XMLTK), a collection of command-line tools providing highly scalable XML data processing.

1 Introduction

Several applications of XML stream processing have emerged recently: content-based XML routing [38], selective dissemination of information (SDI) [3, 8, 11], continuous queries [9], and processing of scientific data stored in large XML files [23, 39, 32]. They commonly need to process a large collection of XPath expressions (say 10,000 to 1,000,000), on a continuous stream of XML data, at a high sustained throughput.

For illustration, consider XML Routing [38]. Here a network of XML routers forwards a continuous stream of XML packets from data producers to consumers. A router forwards each XML packet it receives to a subset of its output

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links (other routers or clients). Forwarding decisions are made by evaluating a large number of XPath filters, corresponding to clients' subscription queries, on the stream of XML packets. Data processing is minimal: there is no need for the router to have an internal representation of the packet, or to buffer the packet after it has forwarded it. Performance, however, is critical, and [38] reports very poor performance with publicly available XPath processing tools.

Our goal is to develop techniques for evaluating a large collection of XPath expressions on a stream of XML packets. First we describe a technique that guarantees a sustained throughput, which is largely independent of the number of XPath expressions. In contrast, in all other techniques proposed for processing XPath expressions the throughput decreases as the number of XPath expressions increases. [3, 8, 11]. Second, we describe a lightweight binary data structure, called Stream IndeX (SIX), which can be added to the XML packets for further speedups.

The first and main contribution is to show that a Deterministic Finite Automaton (DFA) can be used effectively to process a large collection of XPath expressions, at guaranteed throughput. Our approach is to convert all XPath expressions into a single DFA, then evaluate it on the input XML stream. DFAs are the most efficient means to process XPath expressions, but they were thought to be useless for workloads with a large number of XPath expressions, because their size grows exponentially with size of the workload.

Our solution to the state explosion problem consists of constructing the DFA lazily. A lazy DFA is one whose states and transitions are computed from the corresponding NFA at runtime, not at compile time. A new entry in the transition table or a new state is computed only when the input data requires the DFA to follow that transition or enter that state. The transitions and states in the lazy DFA form a subset of those in the standard DFA, which we call eager DFA in this paper. As a consequence, the lazy DFA can sometimes be much smaller than the eager DFA.

We show that, for XML processing, the number of states in the lazy DFA is small and depends only on the structure of the XML data. It is largely independent on the number of XPath expressions in the workload. More precisely, the size of the lazy DFA is at most the size of the data guide [17] of the XML data, which is typically very small for XML data that has a fairly regular structure. In hindsight, after we first announced this result in [19], this fact may sound obvious, but it was far from obvious before. Previous work in this area [3, 8, 11] explicitly avoided using DFAs, and developed alternative processing techniques that are slower, but have guaranteed space bounds.

To support the claim that the number of states in the lazy DFA is small, we present here a series of theoretical results characterizing the size of both the eager and the lazy DFA for XPath expressions. These results are of general interest in XPath processing, beyond stream applications.

The second contribution in this paper consists of a light-weight technique for speeding up processing XML documents in a network application. The observation here is that, in many applications processing streams of XML messages, the main bottleneck consists of parsing, or tokenizing each message. To address
that, some companies use a proprietary tokenized format instead of the XML text representation [15], but this suffers from lack of interoperability. We propose a more lightweight technique, that adds a small amount of binary data to each XML document, facilitating access into the document. We call this data a Stream Index (SIX). The SIX is computed once, when the XML document is first generated, and attached somehow to the document (for example using DIME [13]). All applications receiving the document that understand the SIX can then access the XML data much faster. If they don’t understand the SIX, then they can fall back on the traditional parse/evaluate model. Space-wise, the overhead of a SIX is very small (typical values are, say, 7% of the data, and can be reduced further), so there is little or no penalty from using it. We note that the general principle of adding a small amount of binary data to facilitate access in the XML document also admits other implementations, see [20, 22].

Finally, we illustrate an application of our techniques by describing the XML Toolkit (XMLTK), for highly scalable processing of XML files. Our goal is to provide to the public domain a collection of stand-alone XML tools, in analogy with Unix commands for text files. Current tools include sorting, aggregation, nesting, unnesting, and a converter from a directory hierarchy to an XML file. Each tool performs one single kind of transformation, but can scale to arbitrarily large XML documents in, essentially, linear time, and using only a moderate amount of main memory. By combining tools in complex pipelines users can perform complex computations on the XML files. There is a need for such tools in user communities that have traditionally processed data formatted in line-oriented text files, such as network traffic logs, web server logs, telephone call records, and biological data. Today, many of these applications are done by combinations of Unix commands, such as grep, sed, sort, and awk. All these data formats can and should be translated into XML, but then all the line-oriented Unix commands become useless. Our goal is to provide tools that can process the data after it has been migrated to XML.

Discussion This paper focuses only on linear XPath expressions. Applications rarely have such simple workloads, and are more likely to use XPath expressions with nested predicates. Scalable techniques for such workloads require a separate investigation and are out of the scope of this paper. However, the techniques described here are relevant to the general XPath processing problem, for two reasons. First, processing linear expressions is a subproblem in processing more complex workloads, and needs to be addressed somehow. In fact we describe here a simple way to evaluate XPath expressions with nested predicates by decomposing them into linear fragments, and we found this simple technique to work well on small workloads. Second, at a deeper level, it has been shown in [21] that our results about the DFA extend, although not in a trivial way, to a pushdown automaton, which can process an arbitrarily complex workload of XPath expressions with nested predicates. Thus, the results and techniques discussed in this paper can be seen as building blocks for more powerful processors.

Paper Organization We begin with an overview in Sec. 2 of the processing model and the system’s architecture. We describe in detail processing with a
DFA in Sec. 3, then discuss its construction in Sec. 4 and analyze its size. We describe the SIX in Sec. 5. We report our experimental results in Sec. 6 and describe the XML Toolkit in Sec. 7. Sec 8 contains related work, and we conclude in Sec. 9. The Appendix contains some of the proofs and more details on the XML Toolkit.

2 Overview

2.1 The Event-Based Processing Model

The architecture of our XML stream processing system is shown in Figure 1. The user specifies several correlated XPath expressions arranged in a tree, called the query tree. An input stream of XML packets is first parsed by a SAX parser that generates a stream of SAX events, or SAX tokens; this is sent to the query processor, which evaluates the XPath expressions and generates a stream of application events. The application is notified of these events, and usually takes some action such as forwarding the packet, notifying a client, or computing some values. An optional Stream Index (called SIX) may accompany the XML stream to speed up processing (Section 5).

We consider linear XPath expressions, $P$, given by the following grammar:

$$P ::= /N | //N | PP$$

$$N ::= E | A | * | text() | text() = S$$

Here $E$ and $A$ are element label and attribute label respectively, $/$ denotes the child axis, $//$ denotes the descendant axis, $*$ is the wild card, and $S$ is a string constant. As explained earlier, nested predicates are not discussed here, and have to be decomposed into linear XPath expressions, as shown below.

A query tree, $Q$, has nodes labeled with variables and the edges with linear path expressions. There is a distinguished variable, $\mathcal{R}$, which is always bound to the root node of the XML packet. Each node in the tree also carries a boolean flag, called saxf. When its value is true, then the SAX events under that node are forwarded to the application; otherwise they are not forwarded to the application. The saxf can be set on and off at various nodes in the query tree. The saxf flag is used by the stream index, Sec. 5.

Example 2.1 The following is a query tree (tags taken from the NASA dataset [32]):

```
$D IN $R/datasets/dataset
$H IN $D/history
$T IN $D/title saxf = true
$TH IN $D/tableHead saxf = true
$N IN $D/tableHead/*
$F IN $TH/field
$V IN $N/text()="Galaxy"
```

Fig. 2 shows this query tree graphically. Here the application requests the SAX events under $T$, and $TH$ only. Fig. 3 shows the result of evaluating this
query tree on an XML input stream: the first column shows the XML stream, the second shows the SAX events generated by the parser, and the last column shows the events forwarded to the application. Only some of the SAX events are seen by the application, namely exactly those that occur within a $T$ or $TH$ variable event.

**Nested Predicates** When an XPath expression contains nested predicates, then the application needs to decompose them into linear XPath expressions. For example, given the expression:

```
$X \text{ IN } $R/catalog/product[@category="tools"][sales/@price > 200]/quantity
```

the application needs to decompose it into four linear XPath expression, which form the query tree $Q$ shown in Fig. 4. The query processor will notify the application of five events, $R$, $Y$, $Z$, $U$, $X$, and the application needs to do
extra work to combine these events, as follows. It uses two boolean variables, \( b_1, b_2 \). On a \( Z \) event, it sets \( b_1 \) to true; on a \( U \) event test the following text value and, if it is > 200, then sets \( b_2 \) to true. At the end of a \( Y \) event it checks whether \( b_1 = b_2 = true \). Some extra care is needed for the descendant axis, //.

This simple method works well in the case when there are few XPath expressions, like in the XML Toolkit described in Sec. 7. Workloads with large numbers of XPath expressions and nested predicates require more complex processing techniques, and this is outside of the scope of this paper. We note, however, that the DFA-based processing method that we study in this paper has been incorporated into a highly scalable technique for XPath expressions with nested predicates [21].

**The Event-based Processing Problem** The problem that we address is: given a query tree \( Q \), pre-process it, and then evaluate it on an incoming XML stream. The goal is to maximize the throughput at which we can process the XML stream.

The special case that we will study in Section 4 is that of a query tree in which every XPath expression is absolute, i.e. starts at the root node. In that case we call \( Q \) a *query set*, or simply a *set*, because it just consists of a set of absolute XPath expressions. For the purpose of application events only, a query tree \( Q \) can be rewritten into an equivalent query set \( Q' \), as illustrated in Fig. 4. Moreover the DFAs for \( Q \) and \( Q' \) are isomorphic, so it suffices to study the size of the DFA only for absolute path expressions (Sec. 4). However, in practice the DFA for \( Q \) is somewhat more efficient to compute than that for \( Q' \), and for
Figure 4: A query tree $Q$ and an equivalent query set $Q'$ of absolute XPath expressions.

that reason the query processor works on the query tree $Q$ directly.

3 Processing with DFAs

3.1 Generating a DFA from a Query Tree

Our approach is to convert a query tree into a Deterministic Finite Automaton (DFA). Recall that the query tree may be a very large collection of XPath expressions: we convert all of them into a single DFA. This is done in two steps: convert the query tree into a Nondeterministic Finite Automaton (NFA), then convert the NFA to a DFA. We review here briefly the basic techniques for both steps and refer the reader to a textbook for more details, e.g. [24]. Our running example will be the query tree $P$ shown in Fig. 5(a). Fig. 5(b) illustrates the first step: converting the query tree to an NFA, denoted $A_n$. We follow a popular method for converting XPath expression into an NFA, which was used in Tukwila [25], our own work [19], and in YFilter [11]; for a detailed overview of various methods for converting a regular expression to an NFA we refer to Watson’s survey [41]. In Fig. 5(b), the transitions labeled $*$ correspond to $*$ or // in $P$; there is one initial state; there is one terminal state for each variable ($X, Y, \ldots$); and there are $\varepsilon$-transitions. The latter are needed to separate the loops from the previous state. For example if we merge states 2, 3, and 6 into a single state then the $*$ loop (corresponding to //) would incorrectly apply to the right branch. This justifies $2 \overset{\varepsilon}{\rightarrow} 3$; the other $\varepsilon$-transitions are introduced by compositional rules, which are straightforward and omitted. Notice that, in general, the number of states in the NFA, $A_n$, is proportional to the size of $P$.

Let $\Sigma$ denote the set of all tags, attributes, and text constants occurring in the query tree $P$, plus a special symbol $\omega$ representing any other symbol that could be matched by $*$ or //$. For $w \in \Sigma^*$ let $A_n(w)$ denote the set of states in $A_n$ reachable on input $w$. In our example we have $\Sigma = \{a, b, d, \omega\}$, and $A_n(\varepsilon) = \{1\}$, $A_n(ab) = \{3, 4, 7\}$, $A_n(a\omega) = \{3, 4\}$, $A_n(b) = \emptyset$.

The DFA for $P, A_d$, has the following set of states and the following transitions:

$$
\text{states}(A_d) = \{ A_n(w) \mid w \in \Sigma^* \} \quad (2)
$$

$$
\delta(A_n(w), a) = A_n(wa), a \in \Sigma
$$

7
Our running example $A_d$ is illustrated\(^1\) in Fig. 5 (c). Each state has unique transitions, and one optional [other] transition, denoting any symbol in $\Sigma$ except the explicit transitions at that state: this is different from $\ast$ in $A_n$, which denotes any symbol. For example [other] at state $\{3, 4, 8, 9\}$ denotes either $a$ or $\omega$, while [other] at state $\{2, 3, 6\}$ denotes $a, d$, or $\omega$. Terminal states may be labeled now with more than one variable, e.g. $\{3, 4, 5, 8, 9\}$ is labeled $\$Y$ and $\$Z$. A sax$_f$ flag is defined for each DFA state as follows: it value is true if at least one of the NFA states in that DFA state has sax$_f$ = true; otherwise it is false.

### 3.2 The DFA at Run time

One can process an XML stream with a DFA very efficiently. It suffices to maintain a pointer to the current DFA state, and a stack of DFA states. SAX events are processed as follows. On a startElement(e) event we push the current state on the stack, and replace the state with the state reached by following the e transition\(^2\); on an endElement(e) we pop a state from the stack and set it as the current state. Attributes and text values are handled similarly. At any moment, the states stored in the stack are exactly those at which the ancestors of the current node were processed, and at which one may need to come back later when exploring subsequent children nodes of those ancestors. If the current state has any variables associated to it, then for each such variable $V$ we send a startVariable($V$) (in the case of a startElement) or endVariable($V$) (in the case of a endElement) event to the application. If either the current state or the new state we enter has sax$_f$=true, then we forward the SAX event to the application.

No memory management is needed at run time\(^3\). Thus, each SAX event is processed in $O(1)$ time, since a transition lookup is implemented as a hash table lookup, and this technique guarantees the throughput at which it can process the stream of XML packets, independently of the number of XPath expressions. The main issue is the size of the DFA, which we discuss next.

### 4 Analyzing the Size of the DFA

For a general regular expression the size of the DFA may be exponential \([24]\). In our setting, however, the expressions are restricted to XPath expressions defined in Sec. 2.1, and general lower bounds do not apply automatically. We analyze and discuss here the size of the eager and lazy DFAs for such XPath expressions. We call a DFA eager if it is obtained using the standard powerset construction, shown in Eq.(2). We call the DFA lazy if its states and transitions

---

\(^1\)Technically, the state $\emptyset$ is also part of the DFA, and behaves like a “failure” state, collecting all missing transitions. We do not illustrate it in our examples.

\(^2\)The state's transitions are stored in a hash table.

\(^3\)The stack is a static array, currently set to 1024: this represents the maximum XML depth that we can handle.
Figure 5: (a) A query tree $P$; (b) its NFA, $A_n$, and (c) its DFA, $A_d$. 
Figure 6: The NFA (a) and the DFA (b) for $\texttt{\*dfa}$. The NFA (c) and the DFA (with back edges removed) (d) for $//a/\texttt{*/}/*/*$: here the eager DFA has $2^5 = 32$ states.

are constructed at runtime, as we describe in detail in Sec. 4.2. We shall assume first that the XPath expressions have no predicates of the form $\text{text()}=S$, and, as a consequence, the alphabet $\Sigma$ is small, then discuss in Sec. 4.3 the impact of such predicates on the size of the DFA. As explained at the end of Sec.2 we will restrict our analysis to absolute XPath expressions, i.e. to query sets rather than query trees.

4.1 The Eager DFA

Single XPath Expression A single linear XPath expression can be written as:

$$P = p_0//p_1//\ldots//p_k$$

where each $p_i$ is $N_1/N_2/\ldots/N_{n_i}$, $i = 0,\ldots,k$, and each $N_j$ is given by Eq.(1) in Sec. 2.1. We consider the following parameters:

- $k =$ number of $//$s
- $n_i =$ length of $p_i$, $i = 0,\ldots,k$
- $m =$ max # of $*$’s in each $p_i$
- $n =$ length (or depth) of $P$, i.e. $\sum_{i=0,k} n_i$
- $s =$ alphabet size $= |\Sigma|$ 

For example if $P = //a/\texttt{*/}a/\texttt{*/}b/a/\texttt{*/}a/b$, then $k = 2$ ($p_0 = \varepsilon$, $p_1 = a/\texttt{*}$, $p_2 = a/\texttt{*/}b/a/\texttt{*/}a/b$), $s = 3$ ($\Sigma = \{a, b, \omega\}$), $n = 9$ (node tests: $a, *, a, *, b, a, *, a, b$),

and \( m = 2 \) (we have 2 \(*\)’s in \( p_2 \)). The following theorem gives an upper bound on the number of states in the DFA. The proof is in the Appendix.

**Theorem 4.1** Given a linear XPath expression \( P \), define prefix \((P) = n_0\) and body \((P) = (k^2 - 1)(n - n_0)^2 + 2(n - n_0) - n_k + 1)s^m\) when \( k > 0 \), and body \((P) = 1\) when \( k = 0 \). Then the eager DFA for \( P \) has at most prefix \((P) + body(P)\) states. In particular, if \( m = 0 \) and \( k \leq 1 \), then the DFA has at most \((n + 1)s^m\) states.

We first illustrate the theorem in the case where there are no wild-cards \((m = 0)\) and \( k = 1 \). Then \( n = n_0 + n_1 \) and there are at most \( n_0 + 2(n - n_0) - n_1 + 1 = n + 1 \) states in the DFA. For example, if \( p = //a/b/a/a/b, \) then \( k = 1, n = 5: \) the NFA and DFA are shown in Fig. 6 (a) and (b) respectively, and indeed the latter has 6 states. This generalizes to \( //N_1/N_2/.../N_n: \) the DFA has only \( n + 1 \) states, and is an isomorphic copy of the NFA plus some back transitions: this corresponds to Knuth-Morris-Pratt’s string matching algorithm [10].

When there are wild cards \((m > 0)\), the theorem gives an exponential upper bound because of the factor \( s^m \). There is a corresponding exponential lower bound, illustrated in Fig. 6 (c), (d), showing that the DFA for \( p = //a/*/\ldots//b \) has \( 2^6 \) states. It is easy to generalize this example and see that the DFA for \( //a/*/\ldots//b \) has \( 2^{m+1} \) states, where \( m \) is the number of \(*\)’s. While a simple hack enables us to \( //a/*/\ldots//b \) on an XML document using constant space without converting it into a DFA, this is no longer possible if we modify the expression to \( //a/*/\ldots/b \).

Thus, the theorem shows that the only thing that can lead to an exponential growth of the DFA is the maximum number of \(*\)’s between any two consecutive //’s. One expects this number to be small in most practical applications; arguably users write expressions like /catalog//product//color rather than /catalog//product/*//*//*//*//*//*//*//*/color. Some implementations of XQuery already translate a single linear XPath expression into DFAs [25].

**Multiple XPath Expressions** For sets of XPath expressions, the DFA also grows exponentially with the number of expressions containing //’. We illustrate this first, then state the lower and upper bounds.

**Example 4.2** Consider four XPath expressions:

\[
\begin{align*}
X_1 & \text{ IN } R//book//figure \\
X_2 & \text{ IN } R//table//figure \\
X_3 & \text{ IN } R//chapter//figure \\
X_4 & \text{ IN } R//note//figure \\
\end{align*}
\]

The eager DFA needs to remember what subset of tags of \{book, table, chapter, note\} it has seen, resulting in at least \( 2^4 \) states. We generalize this below.

**Proposition 4.3** Consider \( p \) XPath expressions:

\[
\begin{align*}
X_1 & \text{ IN } R//a_1//b \\
\vdots \\
X_p & \text{ IN } R//a_p//b \\
\end{align*}
\]
where \(a_1, \ldots, a_p, b\) are distinct tags. Then the DFA has at least \(2^p\) states.\(^4\)

For all practical purposes, this means that the size of the DFA for a set of XPath expressions is exponential. The theorem below refines the exponential upper bound, and its proof is in the Appendix.

**Theorem 4.4** Let \(Q\) be a set of XPath expressions. Then the number of states in the eager DFA for \(Q\) is at most: 
\[
\sum_{P \in Q} \text{prefix}(P) + \prod_{P \in Q} (1 + \text{body}(P)).
\]
In particular, if \(A, B\) are constants s.t. \(\forall P \in Q, \text{prefix}(P) \leq A\) and \(\text{body}(P) \leq B\), then the number of states in the eager DFA is \(\leq p \cdot A + (1 + B)^p\), where \(p\) is the number of XPath expressions in \(Q\) and \(p'\) is the number of such expressions that contain `//`.

Recall that \(\text{body}(P)\) already contains an exponent, which we argued is small in practice. The theorem shows that the extra exponent added by having multiple XPath expressions is precisely the number of expressions with `//`’s. This result should be compared with Aho and Corasick’s dictionary matching problem [2, 36]. There we are given a dictionary consisting of \(p\) words, \(\{w_1, \ldots, w_p\}\), and have to compute the DFA for the set \(Q = \{/\!/w_1, \ldots, /\!/w_p\}\). Hence, this is a special case where each XPath expression has a single, leading `//`, and has no `*`. The main result in the dictionary matching problem is that the number of DFA states is linear in the total size of \(Q\). Theorem 4.4 is weaker in this special case, since it counts each expression with a `//` toward the exponent. The theorem could be strengthened to include in the exponent only XPath expressions with at least two `//`’s, thus technically generalizing Aho and Corasick’s result. However, XPath expressions with two or more occurrences of `//` must be added to the exponent, as Proposition 4.3 shows. We chose not to strengthen Theorem 4.4 since it would complicate both the statement and proof, with little practical significance.

Sets of XPath expressions like the ones we saw in Example 4.2 are common in practice, and rule out the eager DFA, except in trivial cases. The solution is to construct the DFA lazily, which we discuss next.

### 4.2 The Lazy DFA

The lazy DFA is constructed at run-time, on demand. Initially it has a single state (the initial state), and whenever we attempt to make a transition into a missing state we compute it, and update the transition. The hope is that only a small set of the DFA states needs to be computed.

This idea has been used before in text processing [26], but it has never been applied to large numbers of expressions as required in our applications. A careful analysis of the size of the lazy DFA is needed to justify its feasibility. We prove two results, giving upper bounds on the number of states in the lazy DFA, that are specific to XML data, and that exploit either the schema, or the

---

\(^4\)Although this requires \(p\) distinct tags, the result can be shown with only 2 distinct tags, and XPath expressions of depths \(n = O(\log p)\), using binary encoding of tags.
data guide. We stress, however, that neither the schema nor the data guide need to be known to the query processor in order to use the lazy DFA, and only serve for the theoretical results.

Formally, let $A_l$ be the lazy DFA. Its states are described by the following equation which should be compared to Eq.(2) in Sec. 3.1:

$$\text{states}(A_l) = \{ A_n(w) \mid w \in \mathcal{L}_{\text{data}} \}$$

$$\delta(A_n(w), a) = A_n(wa), wa \in \mathcal{L}_{\text{data}}$$

Here $\mathcal{L}_{\text{data}}$ is the set of all root-to-leaf sequences of tags in the input XML streams. Thus, the size of the lazy DFA is determined by two factors: (1) the number of states, i.e. $|\text{states}(A_l)|$, and (2) the size of each state, i.e. $|A_n(w)|$, for $w \in \mathcal{L}_{\text{data}}$. Recall that each state in the lazy DFA is represented by a set of states from the NFA, which we call an NFA table. In the eager DFA the NFA tables can be dropped after the DFA has been computed, but in the lazy DFA they need to be kept, since we never really complete the construction of the DFA (they are technically needed to apply Equation (4) at runtime). Therefore the NFA tables also contribute to the size of the lazy DFA. We analyze in this section both factors.

### 4.2.1 The number of states in the lazy DFA

The first size factor, the number of states in the lazy DFA may be, in theory, exponentially large, and hence is our first concern. Assuming that the XML stream conforms to a schema (or DTD), denote $\mathcal{L}_{\text{schema}}$ all root-to-leaf sequences allowed by the schema: we have $\mathcal{L}_{\text{data}} \subseteq \mathcal{L}_{\text{schema}} \subseteq \Sigma^*$. We use graph schema [1, 6] to formalize our notion of schema, where nodes are labeled with tags and edges denote inclusion relationships. A graph schema $S$ is a graph with a designated root node, and with nodes labeled with symbols from $\Sigma$. Each path from the root defines a word $w \in \Sigma^*$, and the set of all such words forms a regular language denoted $\mathcal{L}_{\text{schema}}$. Define a simple cycle, $c$, in a graph schema to be a set of nodes $c = \{x_0, x_1, \ldots, x_{n-1}\}$ which can be ordered s.t. for every $i = 0, \ldots, n - 1$, there exists an edge from $x_i$ to $x_{(i+1) \mod n}$. We say that a graph schema is simple, if for any two simple cycles $c \neq c'$, we have $c \cap c' = \emptyset$.

We illustrate with the DTD in Fig. 7, which also shows its graph schema. This DTD is simple, because the only cycles in its graph schema (shown in Fig. 7 (a)) are self-loops. All non-recursive DTDs are simple. Recall that a simple path in a graph is a path where each node occurs at most once. For a simple graph schema we denote $d$ the maximum number of simple cycles that a simple path can intersect (hence $d = 0$ for non-recursive schemes), and $D$ the total number of nonempty, simple paths starting at the root: $D$ can be thought of as the number of nodes in the unfolding\(^5\). In our example $d = 2$, $D = 13$, since the path

---

\(^5\)The constant $D$ may, in theory, be exponential in the size of the schema because of the unfolding, but in practice the shared tags typically occur at the bottom of the DTD structure (see [37]), hence $D$ is only modestly larger than the number of tags in the DTD.
book/chapter/section/table/note intersects two simple cycles, \{table\} and \{note\}, and there are 13 different simple paths that start at the root: they correspond to the nodes in the unfolded graph schema shown in Fig. 7 (b). For a query set \(Q\), denote \(n\) its depth, i.e. the maximum number of symbols in any \(P \in Q\) (i.e. the maximum \(n\), as in Sec. 4.1). We prove the following result in the Appendix:

**Theorem 4.5** Consider a simple graph schema with \(d, D\), defined as above, and let \(Q\) be a set of XPath expressions of maximum depth \(n\). Then the lazy DFA has at most \(1 + D \times (1 + n)^d\) states.

The result is surprising, because the number of states does not depend on the number of XPath expressions, only on their depths. In Example 4.2 the depth is \(n = 2\): for the DTD above, the theorem guarantees at most \(1 + 13 \times 3^2 = 118\) states in the lazy DFA. In practice, the depth is larger: for \(n = 10\), the theorem guarantees \(\leq 1574\) states, even if the number of XPath expressions increases to, say, 100,000. By contrast, the eager DFA may have \(\geq 2^{100000}\) states (see Prop. 4.3). Fig. 6 (d) shows another example: of the 2\(^5\) states in the eager DFA only 9 are expanded in the lazy DFA.

Theorem 4.5 has many applications. First for non-recursive DTDs \((d = 0)\) the lazy DFA has at most \(1 + D\) states\(^6\). Second, in data-oriented XML instances, recursion is often restricted to hierarchies, e.g. departments within departments, parts within parts. Hence, their DTD is simple, and \(d\) is usually small. Finally, the theorem also covers applications that handle documents from multiple DTDs (e.g. in XML routing): here \(D\) is the sum over all DTDs, while \(d\) is the maximum over all DTDs.

The theorem does not apply, however, to document-oriented XML data. These have non-simple DTDs: for example a *table* may contain a *table* or a *footnote*, and a *footnote* may also contain a *table* or a *footnote*. Hence, both \{table\} and \{table, footnote\} are cycles, and they share a node. This is illustrated in Fig. 8 (a). For such cases we give an upper bound on the size of the lazy DFA in terms of data guides \([17]\). Given an XML data instance, the data guide \(G\) is that schema which is (a) deterministic\(^7\), (b) it captures exactly the sequence of labels in the data, \(L_{schema} = L_{data}\), and (c) \(G\) is unfolded, i.e. it is a tree. The latter property is possible to enforce since \(L_{data}\) is finite, hence the data guide has no cycles. Figure 8 illustrates the connection between graph schemas, XML data, and data guides. The graph schema in (a) is non-simple, and shows all possible nestings that are allowed in the data. An actual XML instance in (b) uses only some of these nestings. The data guide in (c) captures precisely these nestings.

Since data guides are graph schemas with \(d = 0\), Theorem 4.5 applies and gives us:

---

\(^6\)This also follows directly from (3) since in this case \(L_{schema}\) is finite and has \(1 + D\) elements: one for \(w = \varepsilon\), and one for each non-empty, simple path.

\(^7\)For each label \(a \in \Sigma\), a node can have at most one child labeled with \(a\).
Figure 7: A simple graph schema for a DTD (a) and its unfolding (b). Here \( D = 13 \) (since the unfolding has 13 nodes) and \( d = 2 \) (since two recursive elements may be nested: a table may contain a note).

Figure 8: A non-simple graph schema (a), an XML instance (b) and its data guide (c).
Corollary 4.6 Let $G$ be the number of nodes in the data guide of an XML stream. Then, for any set $Q$ of XPath expressions the lazy DFA for $Q$ on that XML stream has at most $1 + G$ states.

An empirical observation is that real XML data tends to have small data guides, regardless of its DTD. To understand why, consider the case of XML documents representing structured text, with elements such as footnote, table, figure, abstract, section, where the DTD allows these elements to be nested arbitrarily. Typical documents will have paths like section/table, section/figure, section/figure/footnote, and, hence the dataguide for large enough collection of such documents is quite likely to contain all these paths. However, many other paths are quite unlikely to occur in practice, e.g. table/figure/footnote, figure/section/abstract, and therefore they are unlikely to occur in the dataguide, even though they are technically permitted by the DTD. Thus, the number of nodes in the dataguide is typically much smaller than the theoretical upper bound. This is a general observation, which tends to hold on most practical XML data found in most domains. In order to find a counterexample, one has to go to the domain of Natural Language Processing: Treebank [30] is a large collection of parsed English sentences and its data guide has $G = 340,000$ nodes, as reported in [28].

4.2.2 Size of NFA tables

The following proposition ensures that the NFA tables do not increase exponentially:

Proposition 4.7 Let $Q$ be a set of $p$ XPath expressions, of maximum depth $n$ Then the size of each NFA table in the DFA for $Q$ is at most $2np$.

The proof follows immediately from the observation that the NFA for one XPath expression has $n + k \leq 2n$ states; hence each NFA table may contain at most $2np$. Despite the apparent positive result, the sets of NFA states are responsible for most of the space in the lazy DFA, and we discuss them in Sec. 6.

4.3 Predicates

We now lift the restriction on predicates, and discuss their impact on the number of states in the DFA. Each linear XPath expression can now end in a predicate $\text{text()} = S$, see Eq.(1) in Sec. 2.1. The only difference is that now we can no longer assume that the alphabet $\Sigma$ is small, since the number of distinct strings $S$ in the query workload can be very large. As a matter of notation, we follow the W3C standards and use a rather confusing syntax for the symbol $\text{text()}$. An XPath expression may end in a predicate denoted $\text{text()} = S$; this matches a SAX event of the form $\text{text(S)}$; hence, the predicate becomes a transition labeled $\text{text(S)}$ in the NFA and the DFA.

For a given set of XPath expressions, $Q$, let $\Sigma$ denote the set of all symbols in the NFA for $Q$, including those of the form $\text{text(S)}$. Let $\Sigma_t = \Sigma_t \cup \Sigma_s$, where $\Sigma_t$
contains all element and attribute labels and \( \omega \), while \( \Sigma_s \) contains all symbols of the form \text{text(S)}\). The NFA for \( Q \) has a special, 2-tier structure: first an NFA over \( \Sigma_t \), followed by some \( \Sigma_s \)-transitions into sink states, i.e. with no outgoing transitions. The corresponding DFA also has a two-tier structure: first the DFA for the \( \Sigma_t \) part, denote it \( A^t \), followed by \( \Sigma_s \) transitions into sink states. All our previous upper bounds on the size of the lazy DFA apply to \( A^t \). We now have to count the additional sink states reached by \( \text{text(S)} \) transitions. For that, let \( \Sigma_s = \{ \text{text(S_1)}, \ldots, \text{text(S_q)} \} \), and let \( Q_i, i = 1, \ldots, q, \) be the set of XPath expressions in \( Q \) that end in \( \text{text()} = S_i \); we assume w.l.o.g. that every XPath expression in \( Q \) ends in some predicate in \( \Sigma_s \), hence \( Q = Q_1 \cup \ldots \cup Q_q \). Denote \( A_i \) the DFA for \( Q_i \), and \( A^t_i \) its \( \Sigma_t \)-part. Let \( s_i \) be the number of states in \( A^t_i \), \( i = 1, \ldots, q \). All the previous upper bounds, in Theorem 4.1, Theorem 4.5, and Corollary 4.6 apply to each \( s_i \). We prove the following in the Appendix.

**Theorem 4.8** Given a set of XPath expressions \( Q \), containing \( q \) distinct predicates of the form \( \text{text()}=S \), the additional number of sink states in the lazy DFA due to the constant values is at most \( \sum_{i=1}^{q} s_i \).

### 5 The Stream IndeX (SIX)

Parsing and tokenizing the XML document is generally accepted to be a major bottleneck in XML processing. An obvious solution is to represent an XML document in binary, as a string of binary tokens. In an XML message system, the messages are now binary representations of XML, rather than real XML, or they are converted into binary when they enter the system. Some commercial implementations adopt this approach in order to increase performance [15]. The disadvantage is that all servers in the network must understand that binary format. This defeats the purpose of the XML standard, which is supposed to address precisely the lack of interoperability that is associated with a binary format.

We favor an alternative approach: keep the XML packets in their native text format, and add a small amount of binary data that allows fast access to the document. We describe here one such technique: a different technique based on the same philosophy is described in [22].

#### 5.1 Definition

Given an XML document, a *Stream IndeX* (SIX) for that document is an ordered set of byte offsets pairs:

\[
(\text{beginOffset}, \text{endOffset})
\]

where \( \text{beginOffset} \) is the byte offset of some begin tag, and \( \text{endOffset} \) of the corresponding end tag (relative to the begin tag). Both numbers are represented in binary, to keep the SIX small. The SIX is computed only once, by the producer of the XML stream, attached to the XML packet somehow (e.g. using
the DIME standard [13]), then sent along with the XML stream and used by every consumer of that stream (e.g. by every router, in XML routing). A server that does not understand the SIX can simply ignore it.

The SIX is sorted by beginOffset. The query processor starts parsing the XML document and matches SIX entries with XML tags. Depending on the queries that need to be evaluated, the query processor may decide to skip over elements in the XML document, using endOffset. Thus, a simple addition of two integers replaces parsing an entire subelement, generating all SAX events, and looking for the matching end tag. This is a significant savings.

The SIX module (see Fig. 1 in Sec. 2.1) offers a single interface: skip(k), where \( k \geq 0 \) denotes the number of open XML elements that need to be skipped. Thus skip(0) means “skip to the end of the most recently opened XML element”. The example below illustrates the effect of a skip(0) call, issued after reading <c>:

**XML stream:**

```
<a> <b> <c> <d> </d> </c> <e> </e> </b> <f> ... 
```

<table>
<thead>
<tr>
<th>parser:</th>
</tr>
</thead>
<tbody>
<tr>
<td>skip(0)</td>
</tr>
<tr>
<td>&lt;a&gt; &lt;b&gt; &lt;c&gt;</td>
</tr>
<tr>
<td>&lt;e&gt; &lt;/e&gt; &lt;/b&gt; &lt;f&gt;</td>
</tr>
</tbody>
</table>

while the following shows the effect of a skip(1) call:

**XML stream:**

```
<a> <b> <c> <d> </d> </c> <e> </e> </b> <f> ... 
```

<table>
<thead>
<tr>
<th>parser:</th>
</tr>
</thead>
<tbody>
<tr>
<td>skip(1)</td>
</tr>
<tr>
<td>&lt;a&gt; &lt;b&gt; &lt;c&gt;</td>
</tr>
<tr>
<td>&lt;f&gt; ...</td>
</tr>
</tbody>
</table>

5.2 Using the SIX

A SIX can be used by any application that processes XML documents using a SAX parser.

**Example 5.1** Consider a very simple application counting how many products in a stream of messages have more than 10 complaints:

```
count(/message/product[count(complaint) >= 10])
```

While looking for product, if some other tag is encountered then the application issues a skip(0). Inside a product, the application listens for complaint: if some other tag is read, then issue a skip(0). If a complaint is read then increment the count. If the count is \( \geq 10 \) then issue skip(1), otherwise skip(0).

A DFA can use a SIX effectively. From the transition table of a DFA state it can see what transitions it expects. If a begin tag does not correspond to any transition and its sax_f flag is set to false, then it issues a skip(0). As we show in Sec. 6 this results in dramatic speed-ups.
5.3 Implementation

The SIX is very robust: arbitrary entries may be removed without compromising consistency. Entries for very short elements are candidates for removal because they provide little benefit. Very large elements may need to be removed (as we explain next), and skipping over them can be achieved by skipping over their children, yielding largely the same benefit.

The SIX works on arbitrarily large XML documents. After exceeding $2^{32}$ bytes in the input stream, beginOffset wraps around; the only constraint is that each window of $2^{32}$-bytes in the data has at least one entry in the SIX. The endOffset cannot wrap around: elements longer than $2^{32}$ bytes cannot be represented in the SIX and must be removed.

The SIX is just a piece of binary data that needs to travel with the XML document. Some application decides to compute it and attaches it to the XML document. Later consumers of that document can then benefit from it. In our implementation the SIX is a binary file, with the same name as the XML file and with extension .six. In an application like XML packet routing, the SIX needs to be attached somehow to the XML document, e.g. by using the DIME format [13], and identified with a special tag. In both cases, applications that understand the SIX format may use it, while those that don’t understand it will simply ignore it.

The SIX for an XML document is constructed while the XML text output is generated, as follows. The application maintains a circular buffer containing a tail of the SIX, and a stack of pointers into the buffer. The application also maintains a counter representing the total number of bytes written so far into the XML output. Whenever the application writes a startElement to the XML output, it adds a (beginOffset, endOffset) entry to the SIX buffer, with beginOffset set to the current byte count, and endOffset set to NULL. Then it pushes a pointer to this entry on the stack. Whenever the application writes a endElement to the XML output, it pops the top pointer from the stack, and updates the endOffset value of the corresponding SIX entry to the current byte offset. In most cases the size of the entire SIX is sufficiently small for the application to keep it in the buffer. However, if the buffer overflows, then application fetches the bottom pointer on the stack and deletes the corresponding SIX entry from the buffer, then flushes from the buffer all subsequent SIX entries that have their endOffset value completed. This, in effect, deletes a SIX entry for a large XML element.

5.4 Speedup of a SIX

The effectiveness of the SIX depends on the selectivity. Given a query tree $P$ and an XML stream let $n$ be the total number of XML nodes, and let $n_0$ be the number of selected nodes, i.e. that match at least one variable in $P$. Define
the selectivity as $\theta = n_0 / n$. Examples: the selectivity of the XPath expression `//*` is 1; the selectivity of `/a/b/no-such-tag` is 0 (assuming `no-such-tag` does not occur in the data); referring to Fig. 3, we have $n = 8$ (one has to count only the `startElement()` and `text()` SAX events), $n_0 = 4$, hence $\theta = 0.5$. The maximum speed-up from a SIX is $1/\theta$. At one extreme, the expression `/no-such-tag` has $\theta = 0$, and may result in arbitrary large speed-ups, since every XML packet is skipped entirely. At the other extreme the SIX is ineffective when $\theta \approx 1$.

The presence of `*`’s and, especially, `//`’s may reduce the effectiveness of the SIX considerably, even when $\theta$ is small. For example the XPath expression `//no-such-tag` has $\theta = 0$, but the SIX is ineffective since the system needs to inspect every single tag while searching for `no-such-tag`. In order to increase the SIX’ effectiveness, the `*`’s and `//`’s should be eliminated, or at least reduced in number, by specializing the XPath expressions with respect to the DTD, using query pruning. This is a method, described in [14], by which an XPath expression is specialized to a certain DTD. For example the XPath expression `//a` may be specialized to `/b/c/d/a | /b/e/a` by inspecting how a DTD allows elements to be nested. Query pruning eliminates all `*`’s from the DFA, and therefore increase the effectiveness of the SIX.

6 Experiments

We evaluated our techniques in a series of experiments addressing the following questions. How much memory does the lazy DFA require in practice? How efficient is the lazy DFA in processing large workloads of XPath expressions? And how effective is the SIX?

We used a variety of DTDs summarized in Fig. 9. All DTDs were downloaded from the Web, except `simple`, which is a synthetic DTD created by us. We generated synthetic XML data for each DTD using the generator from `http://www.alphaworks.ibm.com/tech/xmlgenerator`. For three of the DTDs we also found large, real XML data instances on the Web, which are shown as three separate rows in the table: `protein(real)`, `nasa(real)`, `treebank(real)`. For example the row for `protein` represents the synthetic XML data while `protein(real)` the real XML data, and both have the same DTD.

We generated several synthetic workloads of XPath expressions for each DTD, using the generator described in [11]. It allowed us to tune the probability of `*` and `//`, denoted $Prob(*)$ and $Prob(//)$ respectively, and the maximum depth of the XPath expressions, denoted $n$. In all our experiments below the depths was $n = 10$.

Our system was a Dell Dual P-III 700Mhz, 2GB RAM running RedHat 7.1. We compiled the Lazy DFA with the gcc compiler version 2.96 without any optimization options. We also run a different system, YFilter, which was written in Java: here we used Java version 1.4.2_04.
Figure 9: Sources of data used in experiments. Only three real data sets were available.

6.1 Validation of the Size of the Lazy DFA

The goal of the first set of experiments was to evaluate empirically the amount of memory required by the lazy DFA. This is as a complement to the theoretical evaluation in Sec. 4. For each of the datasets we generated workloads of 1k, 10k, and 100k XPath expressions, with \( \text{Prob}(\ast) = \text{Prob}(//) = 5\% \) and depth \( n = 10 \).

We first counted the number of states generate in the lazy DFA. Recall that, for simple DTDs, Theorem 4.5 gives the upper bound \( 1 + D \times (1 + n)^d \) on the number of states in the lazy DFA, where \( D \) is the number of elements in the unfolded DTD, \( d \) is the maximum nesting depths of recursive elements, and \( n \) is the maximum depth of any XPath expression. For real XML data, Corollary 4.6 offers the additional upper bound \( 1 + G \), where \( G \) is the size of the dataguide of the real data instance, which, we claimed, is in general small for a real data instance. By contrast, a synthetic data instance may have a very large dataguide, perhaps as large as the data itself, and therefore the upper bound in Corollary 4.6 is of no practical use.

Fig. 10(a) shows the number of states in the lazy DFA on synthetic XML data. The first four DTDs are simple, and the number of states was indeed smaller than the bound in Theorem 4.5, sometimes significantly smaller. For example ebBPSS has 1479 states for 100k XPath expressions, while the theoretical upper bound, taking \( D = 29, d = 2, n = 10 \), is 3510. The last three DTDs were not simple, and Theorem 4.5 does not apply. In two cases (nitf and treebank, for 100,000 expressions) we ran out of memory.

Fig. 10(b) shows the number of states in the lazy DFA for real data. Here

---

<table>
<thead>
<tr>
<th>Source</th>
<th>file size (KB)</th>
<th>max depth</th>
<th>avg depth</th>
<th># of elems. (DTD)</th>
<th># of elems. (XML)</th>
<th>recursive?</th>
<th>simple?</th>
</tr>
</thead>
<tbody>
<tr>
<td>simple</td>
<td>27432</td>
<td>22</td>
<td>19.9</td>
<td>12</td>
<td>359338</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>prov</td>
<td>25624</td>
<td>25</td>
<td>10.0</td>
<td>29</td>
<td>356907</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td><a href="http://www.wapforum.org">www.wapforum.org</a></td>
<td>22952</td>
<td>7</td>
<td>4.6</td>
<td>66</td>
<td>700270</td>
<td>no</td>
<td>yes</td>
</tr>
<tr>
<td>protein</td>
<td>51964</td>
<td>17</td>
<td>8.5</td>
<td>133</td>
<td>439871</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>nitf</td>
<td>8000</td>
<td>13</td>
<td>6.6</td>
<td>109</td>
<td>145146</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>nasa</td>
<td>24488</td>
<td>8</td>
<td>5.5</td>
<td>250</td>
<td>830766</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>treebank</td>
<td>39064</td>
<td>12</td>
<td>11.1</td>
<td>250</td>
<td>830766</td>
<td>yes</td>
<td>no</td>
</tr>
</tbody>
</table>

---

\( ^9 \) We took here \( D \) to be the number of elements in the DTD. The real value of \( D \) may be larger, due to the unfolding.
Figure 10: Size of the lazy DFA for synthetic data (a), and real data (b); average size of an NFA table (c), and of a transition table (d); total memory used by a lazy DFA (e). 1k XPEs means 1000 XPath expressions.
the number of states is significantly smaller than in the previous graph. This is explained by the fact that real XML instances have a small dataguide, which limits the number of states in the lazy DFA. For example, for the real nasa data instance the number of states was 103, 107, and 108 respectively; contrast that to 1470, 2619, 2874 for the synthetic nasa data instance. The only data instance with a large data guide was treebank, where G is about 340,000 and the lazy DFA had 43,438 states on the largest workload (100,000 XPath expressions).

The huge difference between the synthetic and the real data set is striking, and makes one reflect on the limitations of current XML data generators. The lesson for our purposes is that the size of the lazy DFA is small or medium on real data sets, but can be prohibitively large on synthetic data sets.

Next, we measured experimentally the average size of the NFA tables in each DFA state, i.e. the average number of NFA states per DFA state. Fig. 10 (c) shows the experimental results. The average size of the NFA tables grows linearly with p. This is consistent with the theoretical analysis: Proposition 4.7 gives an upper bound of 2np, hence 20p in our case, where p is the number of XPath expressions. The experiments show that bound to be overly pessimistic and the real value to be closer to p/10, however. Even so, the total size of the NFA tables is large, since this number needs to be multiplied with the number of states in the lazy DFA.

We also measured the average number of transitions per DFA state. These transitions are stored in a hash table at each state in the lazy DFA, hence they also contribute to the total size. Notice that the number of transitions at a state is bounded by the number of elements in the DTD. Our experimental results in Fig. 10 (d) confirm that. The transition tables are much smaller than the NFA tables.

Next we measured the total amount of memory used by the lazy DFA, expressed in MB's: this is shown in Fig. 10 (e). The most important observation is that the total amount of memory used by the lazy DFA grows largely linearly with the number of XPath expressions. This is explained by the fact that the number of states is largely invariant, while the average size of an NFA table at each state grows linearly with the workload. We also measured the amount of memory used by a naive NFA, without any of the state sharing optimization implemented in YFilter. The graph shows that this is comparable to the size of the lazy DFA. On one hand the total size of the NFA tables in the lazy DFA is larger than the number of states in the NFA, on the other hand the DFA makes up by having fewer transition tables.

None of the experiments above included any predicates on data values. To conclude our evaluation of the memory usage of the lazy DFA, we measured the impact of predicates. Recall that the theoretical analysis for this case was done in Sec.4.3, and we refer to the notations in that section. We generated a workload of 200000 XPath expressions with constant values. We used a subset of size 9.12MB of the protein data set, and selected randomly constants that actually occur in this data. In order to select values randomly from this data instance we had to store the entire data in main memory. For that reason, we used only a subset of the protein data set. The number of distinct constants
used was $q = 29740$. The first tier of the automaton had 80 states (slightly less than Fig. 10 (b) because we used only a fragment of the protein data), while the number of additional states was 63412 states. That is, each distinct constant occurring in the predicates contributed to approximatively two new states in the second tier of the automaton. The average size of the NFA tables at these states is at most as large as the average number of XPath expressions containing each distinct constant, i.e. \( 200000/29740 \approx 6.7 \). Since these states have no transition tables, each distinct value occurring in any of the predicates used about \( 13.4 + 4 \approx 54 \) bytes of main memory. While non-negligible, this amount is of the same order of magnitude as the predicate itself.

### 6.2 Throughput

In our second sets of experiments we measured the speed at which the lazy DFA processes the real XML data instances nasa and protein. Our first goal here was to evaluate the speed of the lazy DFA during the stable phase, when most or all of its states have been computed, and the lazy DFA reaches its maximum speed. Our second goal was to measure the length of the warmup phase, when most time is spent constructing new DFA states. To separate the warmup phase from the stable phase, we measured the instantaneous throughput, as a function of the amount of XML data processed: we measured at 5MB intervals for nasa and 100MB intervals for protein, or more often when necessary.

We compared the lazy DFA to YFilter [11], a system that uses a highly optimized NFA to evaluate large workloads of XPath expressions. There are many factors that make a direct comparison of the two systems difficult: the implementation language (C++ for the lazy DFA v.s. Java for YFilter), the XML parser (a custom parser v.s. the Xerces Java parser), and different coding styles. While a perfect calibration is not possible, in order to get a meaningful comparison we measured the throughput of the Xerces C++ SAX and SAX2 parsers, the Xerces Java SAX and SAX2 parsers, and the parser of the lazy DFA. The results are shown in Fig. 11. Contrary to our expectations, the Xerces C++ SAX parser was slightly slower than the Java SAX Parser, while the C++ SAX2 parser was even slower. Assuming that the Java and C++ version used identical algorithms, this suggests that a Java program should run slightly faster than a C++ program on our platform. On the other hand the lazy DFA parser was faster on average than the Xerces Java SAX2 parser (used by YFilter), hence, all things being equal, the lazy DFA should run slightly faster than YFilter (at least on nasa). While these numbers underly the difficulty of a direct comparison, they also suggest that any the difference in the throughput of the two systems that are attributable to the implementation language and the parser are relatively small. Therefore we report below absolute values of the throughput and do not attempt to normalize them.

In Fig. 12 (a) and (b) we show the results for workloads of varying sizes (500 to 500,000 XPath expressions for nasa, 1,000 to 1,000,000 for protein). In all workloads the maximum depth was $n = 10$, and $Prob(s) = Prob(//) = 0.1$. The most important observation is that in both graphs the lazy DFA reached
indeed a stable phase, after processing about 5-10MB of nasa data or 50MB of protein data, where the throughput was constant, i.e. independent on the size of the workload. The throughput in the stable state was about 3.3-3.4Mb/s for nasa and about 2.4Mb/s for protein.

By contrast, the throughput of YFilter decreases with the number of XPath expressions: as the workload increases by factors of 10, the throughput of YFilter decreases by an average factor of 2. In general, however, the throughput of the lazy DFA is consistently higher than that of YFilter, by factors ranging from 4.6 to 48. The throughput was especially higher for large workloads.

The high throughput of the lazy DFA should be balanced by two effects: the amount of memory used and the speed of the warmup phase. To get a sense of the first effect, notice that the lazy DFA used almost the entire 2GB of main memory on our platform in some of the tests. In one case, when we tried to run it on the nasa dataset with 1,000,000 XPath expressions, we ran out of memory\(^\text{10}\). By contrast, YFilter never used more than 60MB of main memory on any workload.

To see the second effect, we report the total running time of the entire data instance in Fig. 13 (a). The gains of the lazy DFA over YFilter are now smaller, between factors of 1.6 and 8.3. In one case, YFilter was faster than the lazy DFA by a factor of 2. Notice that protein is much larger, allowing the lazy DFA more time to recover from the high warmup cost: here the lazy DFA was always faster. The difference from the graphs in Fig. 12 is explained by the fact that the warmup phase is expensive.

Next, we ran similar experiments testing the sensitivity of the lazy DFA to increasing numbers of ‘∗’s and ‘//’s in the workload of XPath expressions. Figures 12 (c) and (d) show the variation of the throughput when \(\text{Prob}(\ast)\) or \(\text{Prob}(//)\) vary. We only show here the results for the nasa dataset; those for protein were similar. These graph show the same general trend as those in Figure 12 (a) and (b). One interesting observation here is that the warmup phase of the lazy DFA is not affected by the presence of ‘∗’s, only by that of ‘//’s.

A type of workload of particular interest in practice is one without any

\(^{10}\text{The same test, however, runs fine on a Solaris platform, since the Solaris operating system has a better memory management module. The overall throughput of the lazy DFA was also higher on the Solaris platform. In a preliminary version of this work [19] we reported experiments on a Solaris platform.}\)
occurrences of * and //. We ran a similar set of experiments on such workloads, and we report the results in Fig. 12 (e) and (f). We also report the absolute running times in Fig. 13 (b). On such a workload both the NFA optimized by YFilter and the DFA become two isomorphic Trie structures. As before, the lazy DFA is slow during the warmup phase, which determined one total running time to be less than for YFilter in Fig. 13 (b).

6.3 Evaluation of the SIX

In this set of experiments we evaluated the SIX on synthetic nitf data\textsuperscript{11}, with 10000 XPath expressions using 0.2% probabilities for both the // and the *’s. The justification for these low values is based on the discussion at the end of Sec. 5.4: the SIX is ineffective for workloads with large numbers of // and *, and there exists techniques (e.g. query pruning) for eliminating both // and * by using a schema or a DTD. In order to vary the selectivity parameter $\theta$ (Sec. 5.4), we made multiple, disjoint copies of the nitf DTD, and randomly assigned each XPath expression to one such DTD: $\theta$ decreases when the number of copies increases. We generated about 50MB of XML data, then copied it to obtain a 100MB data set. The reason for the second copy is that we wanted to measure the SIX in the stable phase, while the lazy DFA warms up too slowly when using a SIX, because it sees only a small fragment of the data. The size of complete SIX for the entire dataset was 6.7MB, or about 7% of the XML data.

Fig. 14 (a) shows the throughput with a SIX, and without a SIX, for all three selectivities. Without a SIX the throughput was constant at around 5MB/s. This is slightly higher than for the previous experiments because of our optimization of the “failure state” transitions: when the lazy DFA enters the failure state, where all transitions lead back to itself, the lazy DFA processor does not lookup the next state in the transition table (which is a hash table, in this case with only one entry), but simply keeps the same current state.

When ran with a SIX, the throughput increased significantly for low selectivities. For $\theta = 0.03$ the throughput oscillated around 16-19MB/s, resulting in an average speed-up of 3.3. Notice that the throughput of the lazy DFA with a SIX was higher in all cases, even significantly higher than the parser’s throughput, which was around 6.8MB/s. This is because the SIX allows large portions of the XML document to be skipped entirely, thus can be faster than parsing the entire document.

Next, we measured how much we can decrease the SIX by removing entries corresponding to small XML elements. Reducing the size is important for a stream index, since it competes for network bandwidth with the data stream. Fig. 14 (b) shows the throughput as a function of the cut-off size for the XML elements. The more elements are deleted from the SIX, the smaller the throughput. However, the SIX size also decreases, and does so much more dramatically. For example at the 1k data point, when we deleted from the SIX all elements whose size is $\leq$ 1k bytes, the throughput decreases to 14MB/s from a high of

\textsuperscript{11}http://www.nitf.org/site/nitf-documentation/
Figure 12: The throughput of the lazy DFA and YFilter, as a function of the amount of XML data consumed. Varying workload sizes (a), (b); varying probabilities for * and // (c), (d); workloads without * and // (e), (f). Here 1k XPE means 1000 XPath expressions.
Prob (*) = 10%, Prob (//) = 10%

<table>
<thead>
<tr>
<th></th>
<th>nasa</th>
<th></th>
<th>protein</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>lazyDFA</td>
<td>YFilter</td>
<td>lazyDFA</td>
<td>YFilter</td>
</tr>
<tr>
<td>500</td>
<td>7.14</td>
<td>30.73</td>
<td>1,000</td>
<td>289.52</td>
</tr>
<tr>
<td>5,000</td>
<td>9.99</td>
<td>60.79</td>
<td>10,000</td>
<td>285.88</td>
</tr>
<tr>
<td>50,000</td>
<td>54.89</td>
<td>129.54</td>
<td>100,000</td>
<td>355.41</td>
</tr>
<tr>
<td>500,000</td>
<td>602.68</td>
<td>323.58</td>
<td>1,000,000</td>
<td>3899.58</td>
</tr>
</tbody>
</table>

Figure 13: Absolute running times in seconds for workloads with (a) and without (b) occurrences of * and //.

Throughput Improvements from SIX (Stable State)

<table>
<thead>
<tr>
<th></th>
<th>Theta = 3%</th>
<th>Theta = 3% (SIX)</th>
<th>Theta = 8%</th>
<th>Theta = 8% (SIX)</th>
<th>Theta = 14%</th>
<th>Theta = 14% (SIX)</th>
<th>Parser</th>
</tr>
</thead>
<tbody>
<tr>
<td>Throughput (MB/s)</td>
<td>20</td>
<td>19</td>
<td>25</td>
<td>25</td>
<td>20</td>
<td>20</td>
<td></td>
</tr>
<tr>
<td>XML Stream (MB)</td>
<td>50</td>
<td>50</td>
<td>60</td>
<td>60</td>
<td>70</td>
<td>70</td>
<td></td>
</tr>
</tbody>
</table>

Effect of Decreasing SIX Size

<table>
<thead>
<tr>
<th>Size of XML elements deleted from SIX</th>
<th>Throughput (MB/s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0k</td>
<td>8000</td>
</tr>
<tr>
<td>1k</td>
<td>7300</td>
</tr>
<tr>
<td>2k</td>
<td>7000</td>
</tr>
<tr>
<td>3k</td>
<td>6800</td>
</tr>
<tr>
<td>4k</td>
<td>6600</td>
</tr>
<tr>
<td>5k</td>
<td>6400</td>
</tr>
<tr>
<td>6k</td>
<td>6200</td>
</tr>
<tr>
<td>7k</td>
<td>6000</td>
</tr>
<tr>
<td>8k</td>
<td>5800</td>
</tr>
<tr>
<td>9k</td>
<td>5600</td>
</tr>
<tr>
<td>10k</td>
<td>5400</td>
</tr>
</tbody>
</table>

Figure 14: Throughput improvement from the SIX (a), and the effect of decreasing the SIX size by deleting “small” XML elements (b).

19MB/s, but the size of the SIX decreases to a minuscule 898 bytes, from a high of 6.7KB. Thus we can reduce the SIX more than seven times, yet retain 73% of the benefit in the throughput. The explanation is that although the number of elements that can be skipped decreases, their average size increases. In other words, we only miss the short elements, which are not very useful to the SIX.
anyway.

6.4 Discussion

Our experiments demonstrate clearly that the DFA technique is effective at processing XML data at a high, sustained throughput. The most important property is that the throughput remains constant as the number of XPath expressions in the workload increases. This makes the technique attractive for applications that need to guarantee a certain throughput, independently of the size of the workload.

The experiments also show that by computing the DFA lazily one avoids, in most cases of practical interest, an exponential state explosion. We have proven two theoretical upper bounds on the number of states of the lazy DFA. Our experiments confirmed a small number of states in both cases. However, the existence of “bad” cases, i.e. data instance that might cause a state explosion in the lazy DFA, is not completely ruled out. One can generate such XML instances synthetically, but it is unclear whether such instances exists in practice: the only instance we found that caused the number of states to grow into the tens of thousands was *treebank*, whose complex structure is specific to Natural Language, and is not typical in XML data. Still, it is wise to implement a safety valve in a lazy DFA processor, for example by deleting all states and restarting from the initial state when it runs out of memory.

On the downside, our experiments have pointed out two limitations in our current implementation of the lazy DFA: a rather high warmup cost, and large memory consumption by the NFA states. We discuss here both limitations and possible solutions.

**Warmup** First, let us address the high cost of the warmup phase. During this phase the lazy DFA acts precisely like an NFA, only it has to memorize all states it sees. Currently, our implementation of the NFA is very simple, without any optimizations, and this leads to a high warmup cost. In contrast, YFilter consists of an optimized version of the NFA, and it runs much faster than the lazy DFA during warmup. YFilter first constructs an NFA for each XPath expressions in the workload, then identifies common prefixes and eliminates them. For example if given the two expressions /a//b/*/a//c and /a//b/*/a/c, YFilter would optimize the NFA to share states and transitions for their common prefix /a//b/*/a, and only branch at the /c and //c transitions. When extended to large workloads, this optimization results in significant space and time savings over a naive NFA approach. The solution here is to apply the same optimization to the NFA used by the lazy DFA. It suffices to replace the currently naive NFA with YFilter’s optimized NFA, and leave the rest of the lazy DFA unchanged. This would speed up the warmup phase considerably, making it comparable to YFilter, and would not affect the throughput in the stable phase.

With or without optimizations, the manipulation of the NFA tables is expensive, and we have put a lot of thought into their implementation. There are three operations done on NFA tables: create, insert, and compare. To illustrate their complexity, consider an example where the lazy DFA ends up
having 10,000 states, each with an NFA table with 30,000 entries, and that the alphabet Σ has 50 symbols. Then, during warm-up phase we need to create $50 \times 10,000 = 500,000$ new sets; insert 30,000 NFA states in each set; and compare, on average, $500,000 \times 10,000/2$ pairs of sets, of which only 490,000 comparisons return true, the others return false. We found that implementing sets as sorted arrays of pointers offered the best overall performance. An insertion takes $O(1)$ time, because we insert at the end, and sort the array when we finish all insertions. We compute a hash value (signature) for each array, thus comparisons with negative answers take $O(1)$ in virtually all cases.

Memory Second, we will discuss the high memory consumption of the lazy DFA. As our experiments show, this is due to the NFA tables, not the number of states in the lazy DFA. There are several possible approaches to address this, but studying their effectiveness remains part of future work. The simplest one is to adopt the YFilter optimizations as explained above; in addition to speeding up the warmup phase this can also decrease the average size of the NFA tables. A second is to delete the NFA tables from “completed” DFA states. A completed DFA state is one in which all its transitions have already been expanded. The NFA table in a DFA state is only needed when a new transition is followed, in order to construct the new destination DFA state. Once all such transitions have been expanded, there is no more need for the NFA table.

We notice however that, when run on smaller workloads, the lazy DFA uses far less memory than many other systems. Peng and Chwawathe [35] evaluate the throughput and the memory usage of seven systems, including the XML Toolkit (which is based on the lazy DFA and is described here in Sec. 7). In their evaluation the XML Toolkit used by far the least amount of memory, some cases by several orders of magnitude.

Finally, we discuss here the effectiveness of the SIX. Like with any index, it only benefits queries or workloads that retrieve only a very small portion of the data. Our experiments showed the SIX to be effective for workload of 10,000, but on a dataset where we decreased the selectivity artificially. In order to use the SIX in an application like XML packet routine, one needs to cluster XPath expressions into workloads in order to reduce the $\theta$ factor for each workload. When this is possible, then the SIX can be very effective.

7 An application: the XML Toolkit (XMLTK)

We describe here an application of our XPath processing techniques, to a set of tools for highly performant processing of large XML files. The XML Toolkit is modeled after the Unix tools for processing text files, and is available at http://xmltk.sourceforge.net.

The tools currently in the XML Toolkit are summarized in Fig. 15. Every tool inputs/outputs XML data via standard i/o, except file2xml which takes a directory as an input and outputs XML to the standard output.

The xsort tool is by far the most complex one and we describe it in more detail. The others are briefly illustrated in the Appendix, but we note that
most can be used in quite versatile ways [5]. When illustrating the tools we will refer to the DBLP database [27]. We used a dataset with 256599 bibliographic entries.

### 7.1 Sorting

The command below sorts the entries in the file dbpl.xml in ascending order of their year of publication:\footnote{Unix shells interpret the wild-cards, so the command should be given like: `xsort -c /dblp -e "*" ...`. We omit the quotation marks throughout the paper to avoid clutter.}

```bash
xsort -c /dblp -e * -k year/text() dbpl.xml > sorted-dbpl.xml
```

The first argument, `-c`, is an XPath expression that defines the context: this is the collection under which we are sorting: in our example this matches the root element, `dblp`. The second argument, `-e`, specifies the items to be sorted under the context: on the DBLP data this matches elements like the `book`, `inproceedings`, `article`, etc. Finally, the last argument, `-k`, defines the key on which we sort the items; in our example this is the text value of the `year` element. The result of this command is the file `sorted-dbpl.xml` which lists the four publications in increasing order of the `year`. In case of publications with the same years, the document order is preserved.

The command arguments for `xsort` are shown in Fig. 15, with some details omitted. There can be several context arguments (`-c`), each followed by several item arguments (`-e`), and each followed by several key arguments (`-k`). The semantics is illustrated in Fig. 16. First, all context nodes in the tree are

*Table 1: New tools in the XML Toolkit.*

<table>
<thead>
<tr>
<th>Command</th>
<th>Arguments (fragment)</th>
<th>Brief description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>xsort</strong></td>
<td><code>(-c $p (-e $p (-k $p)*))*</code></td>
<td>sorts an XML file</td>
</tr>
<tr>
<td><strong>xagg</strong></td>
<td><code>(-c $p (-a $aggFun $valP)*)*</code></td>
<td>computes the aggregate function $aggFun$ (see Fig. 19)</td>
</tr>
<tr>
<td><strong>xnest</strong></td>
<td>`(-e $p ((-k $p)*</td>
<td>-n $n))*`</td>
</tr>
<tr>
<td><strong>xflatten</strong></td>
<td><code>(-r)? -e $p</code></td>
<td>flattens collections (deletes tags, but not content)</td>
</tr>
<tr>
<td><strong>xdelete</strong></td>
<td><code>-e $p</code></td>
<td>removes elements or attributes</td>
</tr>
<tr>
<td><strong>xpairs</strong></td>
<td><code>(-e $p -g $p)*</code></td>
<td>replicates an element multiple times, pairing it with each element in a collection</td>
</tr>
<tr>
<td><strong>xhead</strong></td>
<td><code>(-c $p (-e $p (-n $n)*))*</code></td>
<td>retains only a prefix of a collection</td>
</tr>
<tr>
<td><strong>xtail</strong></td>
<td><code>(-c $p (-e $p (-n $n)*))*</code></td>
<td>retains only a suffix of a collection</td>
</tr>
<tr>
<td><strong>file2xml</strong></td>
<td><code>-s $dir</code></td>
<td>generates an XML file for the $dir$ file directory hierarchy</td>
</tr>
</tbody>
</table>
Figure 16: Semantics of \texttt{xsort}. Under each context node the item nodes are sorted based on their key. Any nodes that are “between” context nodes and item nodes are omitted from the output.

identified (denoted c in the figure): all nodes that are not below some context node are simply copied to the output in unchanged order. Next, for each context node, all nodes that match that context’s item expressions are identified (denoted e1, e2, ... in the figure), and a key value is computed for each of them, by evaluating the corresponding key expressions. These item nodes are then sorted according to the key values, and output in increasing order of the keys. Notice that the nodes that are below a context but not below an item are omitted from the output.

We illustrate below several examples of \texttt{xsort}.

**Simple sorting** We start with a simple example:
\begin{verbatim}
xsort -c /dblp -e */author -k text()
\end{verbatim}

The answer has the following form, listing all author elements in alphabetical order:
\begin{verbatim}
<dblp>
  <author>...</author>
  <author>...</author>
  ...
</dblp>
\end{verbatim}

**Sorting with multiple key expressions** The following example illustrates the use of two keys. Assuming that author elements have a firstname and a lastname subelement, it returns a list of all authors, sorted by lastname first, then by firstname:
\begin{verbatim}
xsort -c /dblp -e */author
    -k lastname/text() -k firstname/text()
\end{verbatim}

**Sorting with multiple item expressions** When multiple -e arguments are present, items are included in the result in the order of the command line. For example the following command:
Table 1: Experiments with \texttt{xsort}: (a) a global sort, and (b) multiple local sorts. Numbers are running times in seconds. A “-” indicates ran out of memory.

\begin{tabular}{|c|c|c|}
\hline
\textbf{data size (KB)} & \textbf{Xalan (sec)} & \textbf{xsort (sec)} \\
\hline
0.41 & 0.08 & 0.00 \\
4.91 & 0.09 & 0.00 \\
76.22 & 0.27 & 0.02 \\
991.79 & 2.52 & 0.26 \\
9,671.42 & 27.43 & 2.85 \\
100,964.43 & - & 43.97 \\
1,009,964.43 & - & 368.47 \\
\hline
\end{tabular}

\begin{tabular}{|c|c|c|}
\hline
\textbf{data size (KB)} & \textbf{Xalan (sec)} & \textbf{xsort (sec)} \\
\hline
0.41 & 0.08 & 0.00 \\
4.91 & 0.10 & 0.00 \\
76.22 & 0.29 & 0.03 \\
991.79 & 2.78 & 0.35 \\
9,671.42 & 29.42 & 3.54 \\
100,964.43 & - & 35.52 \\
1,009,964.43 & - & 358.47 \\
\hline
\end{tabular}

\texttt{xsort -c /dblp -e * -k title/text()} \hspace{1cm} \texttt{xsort -c /dblp/* -e title -e author -e year -e *}

(a) \hspace{5cm} (b)

By choosing contexts other than the root element we can sort at different depths in the XML document. A common use is to normalize the elements by listing their subelements in a standard order. For example:

\texttt{xsort -c /dblp/* -e title -e author -e url -e *}

This keeps the order of the publication, but reorders their subelements, as follows: first all \texttt{title} elements, then all \texttt{author} elements, then all \texttt{year} elements, and then everything else.

Notice the use of the “catch all” element \texttt{-e *} at the end. We can omit it, and include only selected fields in the result. For example:

\texttt{xsort -c /dblp/* -e title -e author}

retains only the \texttt{title} and \texttt{author} in each publication.

The following example sorts authors alphabetically within each publication:

\texttt{xsort -c /dblp/* -e author -k text() -e *}

\section*{Sorting at deeper contexts}

Finally, multiple context arguments can be specified to sort according to different criteria. For example:

\texttt{xsort -c /dblp/book -e publisher -e title -e *}
\texttt{-c /dblp/*/ -e title -e *}

lists \texttt{publisher} then \texttt{title} first under \texttt{books}, and lists \texttt{title} first under all other publications.
Using the XPath Processor  The XPath expressions in the command line for each tool in the XML Toolkit are converted into a query tree. For illustration, Fig. 17 shows the query tree for the xsort command. The tree has a root variable, one variable for each context, one variable for each item under each context, and one variable for each key under each item under each context. The sax_f flag for all context events is false, because we do not need the SAX events that are between contexts and items (these are omitted from the output).

Implementation  We briefly describe here the implementation of xsort, which we designed to scale to very large XML files. It sorts one context at a time, copying all other elements (not within a context) to the output file in unchanged order. When sorting one context, it creates a global key for each item to be sorted, consisting of the item identification number on the command line, the concatenation of all its keys, and its order number under the current context (to make xsort stable). Next it uses multi-way merge-join, with as much main memory as available, and runs for at most two steps. The first step produces the initial runs, using STL’s priority queue [4], and applying replacement selection [18]. This results in initial runs that may be larger than the main memory; in particular, only one run is produced if the input is already sorted. If more than one run is generated then the second step is executed, which merges all runs to produce the final output. With today’s main memories, practically any XML file can be sorted in only two steps. For example, with 128MB of main memory and disk pages of 4KB, we can sort XML files of up to 4TB [16], and the file size increases quadratically with the memory size. More practical considerations, such as a hard limit of 2GB on file sizes on most systems, or limits on the number of file descriptors, are more likely to limit the size of the largest file we can sort.
Experiments  We evaluated xsort in two experiments\(^\text{13}\), shown in Table 1. We compare xsort with xalan, a publicly available XSLT processor. For xsort we limit the main memory window to 32MB. The first represents a global sort which reorders all bibliographic entries: xsort's running time increases linearly, with the exception of an extra factor of two, when the data size exceeds the memory size. The second table represents local sorts, with small contexts. Here a single pass over the data is always sufficient, and the sorting time increases linearly. The sorting time for xalan also increases linearly, but is an order of magnitude longer than for xsort. Its processing model is DOM-based.

8 Related Work

The problem of evaluating large collections of XPath expressions on a stream of XML documents was first introduced in \cite{3}, for a publish-subscribe system called XFilter. Improved techniques have been discussed in XTrie \cite{8} (based on a trie), our preliminary version of this work \cite{19} (based on lazy DFAs), and YFilter \cite{11} (based on optimized NFAs). In all methods, except ours, there is a space guarantee that is proportional to the total size of all XPath expressions in the workload, but no guarantee on the throughput. Our method makes the opposite tradeoff.

Two optimizations of the lazy DFA are described in \cite{34}. In one, the XPath expressions are clustered according to their axis types (/ or //) at each depth level. This is shown to reduce the number of DFA states: for example, it is shown that by clustering into 8 DFAs, memory usage decreases by a factor of 40 and throughput only by a factor of 8. In the other optimization, NFA tables are allowed to share common subsets, thus saving memory.

More recently, some systems have been described that process more complex XPath expressions \cite{35, 21}, or fragments of XQuery \cite{29, 12}. A complete XQuery engine for streaming data is described in \cite{15}.

A related problem is the event detection problem described in \cite{33}. Each event is a set of atomic events, and they trigger queries defined by other sets of events. The technique used here is also a variation on the Trie data structure.

Ives et al. \cite{25} describe a general-purpose XML query processor that, at the lowest level, uses an event based processing model, and show how such a model can be integrated with a highly optimized XML query processor. We were influenced by \cite{25} in designing our stream processing model. Query processors like \cite{25} can benefit from an efficient low-level stream processor. Specializing regular expressions w.r.t. schemas is described in \cite{14, 31}.

The conversion problem from regular expression to an NFA has been intensively studied in the 60s and 70s: see \cite{41} for a review. The most popular methods is due to Thompson \cite{40} and is adopted by most textbooks.

\(^{13}\)The platform is a Pentium III, 800 MHz, 256 KB cache 128 MB RAM, 512 MB swap, running RedHat Linux 2.2.18, the compiler is gcc version 2.95.2 with the “-O” command-line option, and Xalan-c 1.3.
Empirical studies of the (eager) DFA construction time have been done in the automaton community [42], for NFAs with up to 30 to 50 states.

9 Conclusion

We have described two techniques for processing linear XPath expressions on streams of XML packets: using a Deterministic Finite Automaton, and a Stream Index (SIX). The main problem with the DFA is that the worst case memory requirement is exponential in the size of the XPath workload. We have presented a combination of theoretical results and experimental validations that together prove that the size of the lazy DFA remains small, for all practical purposes. Some of the theoretical results offer insights into the structure of XPath expressions that is of independent interest. We also validated lazy DFAs on streaming XML data and shown that they indeed have a very high throughput, which is independent on the number of XPath expressions in the workload. The SIX is a simple technique that adds some small amount of binary data to an XML document, which helps speed up a query processor by several factors. Finally, we described a simple application of these XPath processing techniques: the XML Toolkit, a collection of command-line tools for highly scalable XML data processing.

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References


A Appendix

A.1 Proof of Theorem 4.1

Proof: Let \( A \) be the NFA for an XPath expression \( P = p_0 // p_1 // \ldots // p_k \) (see notations in Sec. 4.1) and denote \( Q \) its set of states. \( Q \) can be partitioned into \( Q_0 \cup Q_1 \cup \ldots \cup Q_k \), which we call blocks, with the states in \( Q_i = \{ q_{i0}, q_{i1}, q_{i2}, \ldots, q_{in} \} \) corresponding to the symbols in \( p_i \); we have \( \sum_{i=0}^{k} n_i = n \). The transitions in \( A \) are: states \( q_{i0} \) have self-loops with wild-cards, for \( i = 1, \ldots, k \); there are \( \varepsilon \) transitions from \( q_{i-1}n_{i-1} \) to \( q_{i0} \), \( i = 1, \ldots, k \); and there are normal transitions (labeled with \( \sigma \in \Sigma \) or with wild-cards) from \( q_{ij} \) to \( q_{ij+1} \). Each state \( S \) in the DFA \( A_0 \) is defined as \( S = A(w) \) for some \( w \in \Sigma^* \) (\( S \subseteq Q \)). Our goal is to count the number of such states.

Before proving the theorem formally, we illustrate the main ideas on \( P = /a/b//a/*/a//b/a/*/c \), whose NFA, \( A \), is shown in Fig.18. Some possible states are:

\[
\begin{align*}
S_1 &= A(a) = \{ q_{01} \} \\
S_2 &= \{ q_{10}, q_{12} \} = A(a.b.e.e.a.h) \\
S_3 &= \{ q_{10}, q_{12}, q_{20}, q_{21} \} = A(a.b.e.e.a.b.a.e.e.a.b) \\
S_4 &= \{ q_{10}, q_{20}, q_{21} \} = A(a.b.e.e.a.b.a.e.e.b)
\end{align*}
\]

The example shows that each state \( S \) is determined by four factors: (1) whether it consists only of states from block \( Q_0 \), like \( S_1 \), or has states from the other blocks, like \( S_2, S_3, S_4 \); there are \( n_0 \) states in the first category, so it remains to count the states in the second category only. (2) the highest state it reaches, which we call the top: e.g. \( S_2 \) reaches \( q_{12} \), while \( S_3 \) and \( S_4 \) reach \( q_{21} \). We shall see that there are \( n_1 + \ldots + n_k + 1 = n - n_0 + 1 \) possible choices here (since we don’t count \( Q_0 \) any more) (3) the highest local state it reaches in any block, that is the state that is farthest from the beginning of the block. We call this the local top. For example for \( S_3 \) the highest local top is \( q_{12} \), since this is at distance 2 from the beginning of its block, while for \( S_4 \) the highest local top is \( q_{21} \) since this is at distance 1 from the beginning of its block. For each state whose top is in block \( Q_i \), there are at most \( n_1 + n_2 + \ldots + n_{i-1} + 1 \) choices for the local top: the last term, 1, accounts for the fact that if the local top is in the block \( Q_i \) then the local top is equal to the top. (4) the particular values of the wildcards that allowed us to reach that local top (not illustrated here): there are \( s^m \) such choices.

We now make these arguments formal.
Lemma A.1 Let $S = A(w)$ for some $w \in \Sigma^*$. If there exists some $q_{0j} \in S$, for $j = 0, \ldots, n_0 - 1$, then $S = \{q_{0j}\}$.

**Proof:** There are no loops at, and no $\varepsilon$ transitions to the states $q_0, q_1, \ldots, q_{0j}$, hence we have $|w| = j$. Since there are no $\varepsilon$ transitions from these states, we have $S = A(w) = \{q_{0j}\}$.

This enables us to separate the sets $S = A(w)$ into two categories: those that contain some $q_{0j}$, $j < n_0$, and those that don’t. Notice that the state $q_{0n_0}$ does not occur in any set of the first category, and occurs in exactly one set of the second category, namely $\{q_{0n_0}, q_{10}\}$, if $k > 0$ (because of the $\varepsilon$ transition between them), and $\{q_{0m_0}\}$, if $k = 0$ respectively. There are exactly $n_0 = \text{prefix}(P)$ sets $S$ in the first category. It remains to count the sets in the second category, and we will show that there are at most $(k+1)^2(n-n_0)^2 + (n-n_0) + (n-n_0-n_k+1)^m$ such sets, when $k > 0$, and exactly one when $k = 0$: hence, the number of sets of the second category is $\text{body}(P)$, and the total number of states is $\leq \text{prefix}(P) + \text{body}(P)$. We will consider only sets $S$ of the second kind from now on. When $k = 0$, then the only such set is $\{q_{0n_0}\}$, hence we will only consider the case $k > 0$ in the sequel.

Lemma A.2 Let $S = A(w)$. If $q_{de} \in S$ for some $d > 0$, then for every $i = 1, \ldots, d$ we have $q_{0i} \in S$.

**Proof:** This follows from the fact the automaton $A$ is linear, hence in order to reach the state $q_{de}$ the computation for $w$ must go through the state $q_{00}$, and from the fact that $q_{00}$ has a self loop with a wild card.

Lemma A.3 Let $S = A(w)$ and $q_{de} \in S$ for some $d > 0$. Let $q_{ij}$ be a state before $q_{de}$, i.e. $i < d$ or $i = d$ and $j \leq e$. Then, if we split $w$ into $w_1, w_2$ where the length of $w_2$ is $\leq j$, then $q_{0i} \in A(w_1)$.

**Proof:** If the computation for $w$ reaches $q_{de}$, then it must go through $q_{00}, q_{11}, \ldots, q_{ij}$. Hence, if we delete $j$ or fewer symbols from the end of $w$ and call the remaining sequence $w_1$ then the computation for $w_1$ will still reach $q_{0i}$, hence $q_{0i} \in A(w_1)$ because of the selfloop at $q_{0i}$.

We can finally count the maximum number of states $S = A(w)$. We fix a $w$ for each such $S$ (choosing one nondeterministically) and further associate to $S$ the following triple $(q_{de}, q_{tr}, v)$: $q_{de}$ is the top, i.e. the highest state in $S$ (defined by: $\forall q_{ij} \in S$, either $i < d$ or $i = d$ and $j \leq e$); $q_{tr} \in S$ is the local top, i.e. the state with the largest $r$ (defined formally by $\forall q_{ij} \in S$, either $j < r$ or $j = r$ and $i \leq t$; that is, in the case of a tie we choose the largest $t$); finally $v$ is the sequence of the last $r$ symbols in $w$. We claim that the triple $(q_{de}, q_{tr}, v)$ uniquely determines $S$.

First we show that this claim proves the upper bound on the number of sets of the second category, hence proves the theorem. Indeed there are $n_1 + \ldots + n_k + 1 = n - n_0 + 1$ choices for $q_{de}$. This is because in each block $i$ we can choose
q_{i0}, q_{i1}, \ldots, q_{in-1} as top state: we cannot choose q_{in} as top state since this automatically makes q_{(i+1)0} the top state, except when i = k then the top state may be q_{kn} (and this accounts for the ending +1). For each top state q_d, there are \leq n_1 + n_2 + \ldots + n_{d-1} + 1 choices for the local top. This is because if we choose the local top in some block j with j < d then there are \leq n_j choices;

but if we choose the local top in the same block j as the global top, then there is a single choice, namely q_{de}, and this accounts for the ending +1. The total number of choices for (q_{de}, q_{tr}) is bounded by:

\[
\begin{align*}
\sum_{1 \leq j < i \leq k} n_j n_i + \sum_{1}^{k} n_i + \sum_{1}^{k-1} n_i + 1 &= \\
\text{when } q_{de} \neq q_{kn} &\quad= \frac{(\sum_{1}^{k} n_i)^2 - \sum_{1}^{k} n_i^2}{2} + \sum_{1}^{k} n_i + \sum_{1}^{k-1} n_i + 1 \\
\text{when } q_{de} = q_{kn} &\quad\leq \frac{1}{2}(\sum_{1}^{k} n_i)^2 - \frac{1}{k^2}(\sum_{1}^{k} n_i)^2 + \sum_{1}^{k} n_i + \sum_{1}^{k-1} n_i + 1 \\
&\quad= \frac{k^2 - 1}{2k^2} (n - n_0)^2 + (n - n_0) + (n - n_0 - n_k) + 1
\end{align*}
\]

Here we used the inequality:

\[
(\sum_{i=1}^{k} n_i)^2 \leq k^2 \sum_{i=1}^{k} n_i^2
\]

Finally, there are at most \(s^m\) choices for v since these correspond to choosing symbols for the wild cards on the path from q_{t1} to q_{tr}. The total is \((\frac{k^2 - 1}{2k^2} (n - n_0)^2 + (n - n_0) + (n - n_0 - n_k) + 1)s^m\), which, as we argued, suffices to prove the theorem.

It remains to show that the triple \((q_{de}, q_{tr}, v)\) uniquely determines S. Consider two states, \(S, S'\), resulting in the same triples \((q_{de}, q_{tr}, v)\). We have \(S = A(w, v), S' = A(w', v)\) for some sequences \(u, u'\). It suffices to prove that \(S \subseteq S'\) (the inclusion \(S' \subseteq S\) is shown similarly). Let \(q_{ij} \in S\). Clearly \(q_{ij}\) is before \(q_{de}\), and \(j \leq r\). Take out the last \(j\) symbols from \(v\): this is possible since the length of \(v\) is \(r\), hence \(v\) can be written as \(v = v_1, v_2\), with the length of \(v_2\) equal to \(j\). Since \(q_{ij}\) is before \(q_{de}\) and \(q_{de} \in A(w', v)\), by Lemma A.3 we also have \(q_{00} \in A(w', v_1)\). The path from state \(q_{00}\) to state \(q_{ij}\) accepts the word \(v_2\) because \(q_{ij} \in A(w, v_1, v_2)\). Hence, \(q_{ij} \in A(w', v_1, v_2) = S'\).

\[\square\]

A.2 Proof of Theorem 4.4

Proof: Given a set of XPath expressions \(Q\), one can construct its DFA, \(A\), as follows. First, for each \(P \in Q\), construct the DFA \(A_P\). Then, \(A\) is given by the\(^{14}\)There are exactly \(n_j - e\) choices when \(n_j > e\), and 0 choices when \(n_j \leq e\).
Proof: We start by proving some properties of simple graph schemas.

A.3 Proof of Theorem 4.5

Proof: We start by proving some properties of simple graph schemas.

Let \( S \) be a graph schema with symbols from \( \Sigma \) and \( r \) its root node. A path is a sequence of nodes, \( p = (x_0, x_1, \ldots, x_n), n \geq 0 \). Every path consists of at least one node, and we denote \( \text{last}(p) = x_n \) its last node. A rooted path is one that starts at the root, i.e. \( x_0 = r \). A simple path is a path where all nodes are distinct. We define the unfolding of \( S \) to be the graph \( S^u \) whose nodes are all the rooted simple paths in \( S \) and whose edges are pairs \((p, p')\) s.t. (1) there exists an edge in \( S \) from \( \text{last}(p) \) to \( \text{last}(p') \) and (2) either \( p \) is a prefix of \( p' \) or \( p' \) is a prefix of \( p \). The root of \( S^u \) is the rooted simple path \((x_0)\), and the label of some rooted simple path \( p \) in \( S^u \) is the label of \( \text{last}(p) \) in \( S \). Recall that a graph schema is simple if any two simple cycles either have disjoint sets of nodes or are identical.

In the following lemmas we fix \( S \) a simple graph schema and \( p = (x_0, \ldots, x_n) \) a rooted simple path.

Lemma A.4 Let \( C \) be a simple cycle s.t. \( C \cap p \neq \emptyset \). Then there exists \( i \leq j \) s.t. \( C \cap p = \{x_i, x_{i+1}, \ldots, x_j\} \); we call this set an interval and denote it \([i, j]\).

Proof: Let \( x_i \) be the first and \( x_j \) the last node in \( C \cap p \), and suppose \( C \cap p \) has a gap, i.e. \( x_k, x_l \in C \cap p \) but \( x_{k+1}, x_{k+2}, \ldots, x_{l-1} \notin C \). Let \( p' \) be the set of nodes from \( x_k \) to \( x_l \) on the cycle \( C \). Define \( C' = (C - p') \cup \{x_k, x_{k+1}, \ldots, x_l\} \). Clearly \( C' \) is also a simple cycle different from \( C \), and we have \( C \cap C' \neq \emptyset \), contradicting the fact that \( S \) is simple.

Lemma A.5 Let \( C, C' \) be two different simple cycles s.t. \( C \cap p \neq \emptyset \) and \( C' \cap p \neq \emptyset \). Let \([i, j]\) and \([i', j']\) be the intervals as defined in Lemma A.4. Then the intervals \([i, j]\) and \([i', j']\) are disjoint.

Proof: Follows immediately from the fact that \( C \) and \( C' \) are disjoint.

Lemma A.6 Let \( d \) be the number of simple cycles that \( p \) intersects, and denote these cycles \( C_1, \ldots, C_d \). Denote with \( L(p) = \Sigma^+ \) the set of all sequences of labels on all paths in \( S^u \) from the root to \( p \). Then there exists words \( w_0, w_1, \ldots, w_d \in \Sigma^+ \) and \( z_1, \ldots, z_d \in \Sigma^+ \) s.t. \( L(p) = w_0.z_1^+.w_1 \ldots w_{d-1}.z_d^+.w_d. \)
Proof: Let \([i_1, j_1], \ldots, [i_d, j_d]\) be the disjoint intervals obtained by intersecting \(p\) with \(C_1, \ldots, C_d\), i.e. \(p\) has the form:

\[
p = (\ldots, x_{i_1}, \ldots, x_{j_1}, \ldots, x_{i_2}, \ldots, x_{j_2}, \ldots, x_{i_d}, \ldots, x_{j_d}, \ldots)
\]

and each \(C_k\) intersects \(p\) precisely at \(x_{i_k}, x_{i_k+1}, \ldots, x_{j_k}\). Consider any path \(p_0, p_1, \ldots, p_m\) in the unfolded schema \(S^u\) from the root to \(p\), where each \(p_q\) is a simple path in \(S\), \(q = 0, \ldots, m\). Call \(p_q\) good if it is either a prefix of \(p\), or it is of the form \((x_0, \ldots, x_{j_k}, y_1, \ldots, y_l)\), where \(y_1, \ldots, y_l \in C_k\) (i.e. a prefix of \(p\) followed by some fragment of \(C_k\)). We claim that for each \(q\), \(p_q\) is good. In particular \(last(p_q)\) is a node belonging either to \(p\) or to some cycle \(C_k\). If this claim holds, then it suffices to pick each \(w_k\) to be the word between \(x_{i_k}\) and \(x_{i_{k+1}}\) (with \(x_{i_0}\) defined to be \(x_0\) and \(x_{i_{d+1}}\) defined to be \(last(p)\)), and to pick \(z_k\) to be the word on the cycle \(C_k\) when traversed starting at the node \(x_{i_k}\) and it follows that the path \(p_0, p_1, \ldots, p_m\) spells out a word in the language \(w_0, z_1^*, w_1 \ldots w_{d-1}^*, z_d^*, w_d\).

To prove the claim let \(q\) be the largest index for which \(p_q\) is not good. Then \(p_{q+1}\) is good, hence it is a prefix of \(p_q\) (because, if \(p_q\) were a prefix of \(p_{q+1}\), then \(p_q\) were also good). Hence there is a cycle \(C'\) in \(S\) going from \(last(p_{q+1})\) to \(last(p_q)\) and with one edge back to \(last(p_{q+1})\). This cycle is not one of \(C_1, \ldots, C_p\) (otherwise \(p_q\) were the concatenation of \(p_{q+1}\), which is good, and a cycle \(C_k\), and then \(p_q\) were also good). We have already established that \(last(p_{q+1})\) belongs to this cycle. On the other hand, since \(p_{q+1}\) is good, the node \(last(q_{q+1})\) belongs either to \(p\) or to one of the cycles \(C_1, \ldots, C_p\). The first case however contradicts the fact that \(p\) only intersects the cycles \(C_1, \ldots, C_p\), not \(C'\); the second case contradicts the fact that two distinct cycles are disjoint.

Finally, let \(L(S)\) be the regular set of all labels on all rooted path in a graph schema \(S\): we have denoted this \(L_{\text{schema}}\) in Sec. 4.2.1. Then:

**Lemma A.7** If \(S\) is a simple graph schema then \(L(S) = L(S^u)\).

**Proof:** Obviously \(L(S^u) \subseteq L(S)\). For the converse, let \(p = (x_0, x_1, \ldots, x_n)\) be a rooted path in \(S\), and let \(C_1, \ldots, C_d\) be all the simple cycles that it intersects. Reasoning as in the proof of Lemma A.6, \(p\) can be decomposed into \(p = p_0C_1^{m_1}p_1C_2^{m_2}p_2 \ldots C_d^{m_d}p_d\), for some numbers \(m_1, \ldots, m_d > 0\). A similar same path exists then in \(S^u\), hence the word spelled by \(p\) is in \(L(S^u)\).

We now return to the proof of Theorem 4.5. We consider a graph schema \(S\) and, by using Lemma A.7 we can assume that \(S\) is already unfolded, and that Lemma A.6 holds. Then the set of all root-to-leaf sequences allowed by \(S\), \(L(S) \subseteq \Sigma^*\), can be expressed as:

\[
L(S) = \{\varepsilon\} \cup \bigcup_{x \in \text{nodes}} L(x)
\]

where \(L(x)\) denotes all sequences of tags up to the node \(x\) in \(S\). Our goal is to compute the number of states, as given by Eq. (3), with \(L_{\text{data}}\) replaced by
\( \mathcal{L}(S) \). Since the graph schema is simple and each simple path intersects at most \( d \) cycles, we have by Lemma A.6:

\[
\mathcal{L}(x) = \{ w_0 z_1^{m_1} w_1 \ldots z_d^{m_d} w_d \mid m_1 \geq 1, \ldots, m_d \geq 1 \}
\]

(5)

where \( w_0, \ldots, w_d \in \Sigma^* \) and \( z_1, \ldots, z_d \in \Sigma^+. \) (To simplify the notation we assumed that the path to \( x \) intersects exactly \( d \) cycles.) We use a pumping lemma to argue that, if we increase some \( m_i \) beyond \( n \) (the depth of the query set), then no new states are generated by Eq. (3). Let \( u.z^n.v \in \mathcal{L}(x) \) s.t. \( m > n \). We will show that \( A_n(u.z^n.v) = A_n(u.z^n.v) \). Following the transitions in \( A_n \) determined by the sequence \( u.z^n.v \) we notice that the word \( z^n \) must traverse a self-loop in \( A_n \), because \( n \) is the depth; the self-loop, of course, corresponds to a // in one of the XPath expressions. It follows that \( u.z^n.v \) has the same computation in \( A_n \); just follow that loop an additional number of times, hence \( q \in A_n(u.z^n.v) \). Conversely, let \( q \in A_n(u.z^n.v) \) and consider the transitions in \( A_n \) determined by the sequence \( u.z^n.v \). Let \( q' \) and \( q'' \) be the beginning and end states of the \( z^n \) segment. The shortest path from \( q' \) to \( q'' \) in \( A_n \) has at most \( n \) \( \Sigma \cup \{ \ast \} \)-transitions (since the depth of the XPath expression is \( \leq n \)), and at most \( n - 1 \) self-loops. Consider the smallest number \( p \) s.t. \( \forall p_1, p \leq p_1 \leq m \) there is a computation from \( q' \) to \( q'' \) accepting the word \( z^{p_1} \). We will prove that \( p \leq n \). Suppose the contrary, \( p > n \), and consider a computation of \( z^p \) from \( q' \) to \( q'' \). Then the computation must traverse at least one loop \( |z| \) times or more, where \( |z| \geq 1 \) is the length of the word \( z \): for if not, then the word spelled out by the computation has at most length \((n-1)(|z|-1) + n < (n-1)|z| + 1 \), hence it couldn’t spell out the word \( z^p \). Remove exactly \( |z| \) consecutive symbols from \( z^p \) that traverse that self-loop. The remaining word is \( z^{p-1} \) and there exists a computation for it from \( q' \) to \( q'' \), contradicting the fact that \( p \) is minimal such. This proves that \( u.z^n.v \) also has a computation from the initial state in \( A_n \) to \( q \). We have thus concluded that \( A_n(u.z^n.v) = A_n(u.z^n.v) \).

As a consequence, there are at most \((1 + n)^d \) sets in \( \{ A_n(w) \mid w \in \mathcal{L}(x) \} \) (namely corresponding to all possible choices of \( m_i = 0, 1, 2, \ldots, n \), for \( i = 1, \ldots, d \) in Eq. (5)). It follows that there are at most \( 1 + D(1 + n)^d \) states in \( A_i \).

\[\square\]

A.4 Proof of Theorem 4.8

**Proof**: Each state in \( A^i \) can have at most one transition labeled \text{text}(S_i): hence, the number of sink states in \( A_i \) is at most \( s_i \). The automaton for \( Q \cup \ldots \cup Q_q \) is can be described as the cartesian product automaton \( A = A_1 \times \ldots \times A_q \), assuming each \( A_i \) has been extended with the global sink state \( \emptyset \), as explained in Sec. 3.1. The \( \Sigma_q \)-sink states in \( A \) will thus consists of the disjoint union of the \( \Sigma_q \)-sink states from each \( A_i \), because the transitions leading

\[\text{We call them that way in order not to confuse them with the } \emptyset \text{ sink state.}\]
to $\Sigma_s$-sink states in $A_i$ and $A_j$ are incompatible, when $i \neq j$. Hence, there are $\sum_i s_i$ sink states.

\[\square\]

### A.5 Other Tools in the XML Toolkit

All the other tools are designed to do a single pass over the XML data; we illustrate them here only briefly. Some are straightforward, like \texttt{xdelete}; others are quite versatile, like \texttt{xagg}, but we omit more interesting examples for lack of space.

**Aggregation** The \texttt{xagg} command line is given in Fig 15, while some details of the \texttt{-a} argument are given in Fig. 19. We illustrate it here with three examples:

```
xagg -c /dblp -a count text *
xagg -c /dblp -a count text *
  -a count text */author -a avg float */price
xagg -c /dblp/* -a first text title
  -a count text author -a count text url
```

The first example counts the total number of publications under \texttt{dblp}. Its result is:

```
<xagg>
  <context path="/dblp">
```

```
That is, there are 256599 bibliographical entries in the dblp data. The tags xagg, context, and agg are chosen by default and can be overridden in the command line.

The second computes two aggregate functions: the total number of elements, and the average value of price (assuming some publications have a numeric price subelement). Its result will look like in Fig. 20 (a): this is a hypothetical result, in reality the dblp data does not contain prices.

The third computes two aggregate functions for each publication: the first title element and the number of authors. The result will have the form shown in Fig. 20 (b). There will be as many context elements in the result as publications in the input data.
xnest -e /dblp/* -k year/text()

<dblp>
  <group> <key> 2001 </key>
    <book> . . . </book>
    <inproceeding> . . . </inproceedings>
    <inproceeding> . . . </inproceedings>
    . . .
  </group>
  <group> <key> 2000 </key>
    <inproceedings> . . . </inproceedings>
    <article> . . . </article>
    <article> . . . </article>
    <book> . . . </book>
    . . .
  </group>
  <group> <key> 2001 </key>
  . . .
  </group>
</dblp>

Figure 21: Illustration of xnest.

**Collection-oriented operations** The toolkit contains a few collection-oriented tools, inspired from [7]: xnest, xflatten, xpair, and xdelete. The xdelete command simply deletes elements matching one or several XPath expressions. xflatten flattens a nested collection; equivalently, it deletes only the tags, but not the content. For example:

```
xflatten -e //b
```

transforms the input XML document as follows:

from: to:
```
<a> <b> <c> </c> <a> <c> </c>
  <d> </d> <d> </d>
  <b> <e> </e> </b> <b> <e> </e> </b>
</b>
  <c> <d> </d> </c>
  <c> <b> <e> </e> </b> <c> <e> </e> </c>
</a>
```

Only the two top-most b tags are deleted: the flag -r specifies recursive flattening. xnest groups multiple adjacent elements under a new collection: in other words, it inserts new tags in the XML document, without erasing anything. For example:
<directory>
  <name>data</name>
  <file>
    <name>file1</name>
    <filelink xlink:type="simple"
      xlink:href="file://homes/june/suciu/data/file1">
      </filelink>
    <path>/homes/june/suciu/data/file1</path>
    <size>33</size>
    <permissions>-rw------</permissions>
    <type>regular file</type>
    <userid>13750</userid>
    <groupid>330</groupid>
    <lastModification>Wed Nov 21 11:22:23 2001</lastModification>
  </file>
  ...
</directory>

Figure 22: Illustration of file2xml.

xnest -e /dblp/* -k year/text() groups publications based on their year subelement. The output is illustrated in Fig. 21. Here one group is created for every set of adjacent publications that have the same year value. Notice that there may be multiple groups with the same key value, like 2001 above: to have unique groups, one needs to sort first. Multiple keys can be specified, like in xsort. If no key is specified then all adjacent elements are placed under the same group. There is a second variant of xnest that creates groups by their number of elements, see Fig. 15.

Finally, xpair, called pair-with in [7], pairs an element with each item of a collection. For example:

xpair -e /a/b/c -g /a/b/d replaces each occurrence of /a/b/d with an element <pair> <c> </c> <d> </d> </pair>, where the c element is the last it has seen before. Its effect is:
Heads or Tails? \texttt{xhead} and \texttt{xtail} select and output the head or tail of a sequence of elements matching one or several XPath expressions. For example:

\texttt{xhead -c /dblp -e book -n 20 -e article}

outputs only the first 20 \texttt{book} elements and the first 10 (default value) \texttt{article} elements under \texttt{dblp}.

File Directories to XML The \texttt{file2xml} generates an XML file that describes a file directory hierarchy. For example:

\texttt{file2xml -s data > output.xml}

traverses the \texttt{data} directory and all its subdirectories and creates the \texttt{output.xml} document which has an isomorphic structure to the directory hierarchy. The output is shown in Fig. 22.

As another example, the command below lists the top ten largest files in a directory hierarchy:

\texttt{file2xml -s . | xsort -b -c /directory -e //file -k size/text():%i | xhead -c /directory -e file}

The \texttt{%i} option in \texttt{xsort} indicates that \texttt{size} is an integer field.